Introduction to Unification Theory Speeding Up

Temur Kutsia

RISC, Johannes Kepler University of Linz, Austria kutsia@risc.uni-linz.ac.at



Overview

Recursive Descent Algorithm is Expensive

Improvement 1: Linear Space, Exponential Time

Improvement 2. Linear Space, Quadratic Time

Improvement 3. Almost Linear Algorithm



Outline

Recursive Descent Algorithm is Expensive

Improvement 1: Linear Space, Exponential Time

Improvement 2. Linear Space, Quadratic Time

Improvement 3. Almost Linear Algorithm





Example from the Previous Lecture

Example

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

Unifying s and t will create an mgu where each x_i and each y_i is bound to a term with $2^{i+1} - 1$ symbols:

$$\{x_1 \mapsto f(x_0, x_0), x_2 \mapsto f(f(x_0, x_0), f(x_0, x_0)), \dots, y_0 \mapsto x_0, y_1 \mapsto f(x_0, x_0), y_2 \mapsto f(f(x_0, x_0), f(x_0, x_0)), \dots \}$$

- ▶ Problem: Duplicate occurrences of the same variables cause the explosion in the size of terms.
- Fix: Represent terms as graphs which share subterms.





Term Dag

A term dag is a directed acyclic graph such that

- its nodes are labeled with function symbols or variables,
- its outgoing edges from any node are ordered,
- outdegree of any node labeled with a symbol f is equal to the arity of f (nodes labeled with variables have outdegree 0).





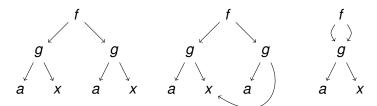
- Convention: Nodes and terms the term dags represent will not be distinguished.
- ► Example: "node" f(a, x) is a node labeled with f and having two arcs to a and to x.



The only difference between various dags representing the same term is the amount of structure sharing between subterms.

Example

Three representations of the term f(g(a, x), g(a, x)):







- ▶ It is possible to build a dag for a given term in O(n) where n is the number of symbols in the term.
- Assumption for the algorithm we plan to consider:
 - ► The input is a term dag representing the two terms to be unified, with unique, shared occurrences of all variables.



Representing substitutions involving only subterms of a term dag:

- Directly by a relation on the nodes of the dag, either
 - stored explicitly as a list of pairs, or
 - by storing a link ("substitution arcs") in the graph itself, and maintaining a list of variables (nodes) bound by the substitution.



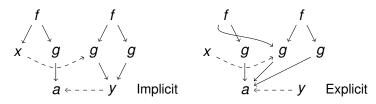


Substitution application. Two alternatives:

- 1. Implicit: Identifies two nodes connected with a substitution arc, without actually moving any of the subterm links.
- Explicit: Expresses the substitution by moving any arc (subterm or substitution) pointing to a variable to point to a binding.

Example

A term dag for f(x, g(a)) and f(g(y), g(y)), and two applications of the substitution $\{x \mapsto g(a), y \mapsto a\}$ on it.







- With implicit application, the binding for a variable can be determined by traversing the graph depth first, left to right.
- Explicit application represents a substitution in a direct way.



Outline

Recursive Descent Algorithm is Expensive

Improvement 1: Linear Space, Exponential Time

Improvement 2. Linear Space, Quadratic Time

Improvement 3. Almost Linear Algorithm





Recursive Descent Algorithm (RDA) on Term Dags

Assumptions:

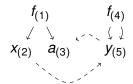
- Dags consist of nodes.
- Any node in a given dag defines a unique subdag (consisting of the nodes which can be reached from this node), and thus a unique subterm.
- Two different types of nodes: variable nodes and function nodes.
- Information at function nodes:
 - ▶ The name of the function symbol.
 - ▶ The arity *n* of this symbol.
 - ► The list (of length *n*) of successor nodes (corresponds to the argument list of the function)
- Both function and variable nodes may be equipped with one additional pointer (displayed as a dashed arrow in diagrams) to another node.





Find:

Takes a node of a dag as input, and follows the additional pointers until it reaches a node without such a pointer. This node is the output of Find.





▶ Find:

Takes a node of a dag as input, and follows the additional pointers until it reaches a node without such a pointer. This node is the output of Find.



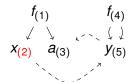




▶ Find:

Takes a node of a dag as input, and follows the additional pointers until it reaches a node without such a pointer. This node is the output of Find.

- ► Find(3)=(3)
- ► Find(2)=







▶ Find:

Takes a node of a dag as input, and follows the additional pointers until it reaches a node without such a pointer. This node is the output of Find.

- ► Find(3)=(3)
- ► Find(2)=



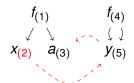




▶ Find:

Takes a node of a dag as input, and follows the additional pointers until it reaches a node without such a pointer. This node is the output of Find.

- ► Find(3)=(3)
- ► Find(2)=







▶ Find:

Takes a node of a dag as input, and follows the additional pointers until it reaches a node without such a pointer. This node is the output of Find.

- ► Find(3)=(3)
- ► Find(2)= (3)







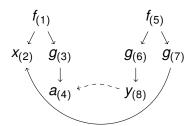
▶ Union:

Takes as input a pair of nodes u, v that do not have additional pointers and creates such a pointer from u to v.



▶ Occur:

Takes as input a variable node u and another node v (both without additional pointers) and performs the occur check, i.e. it tests whether the variable is contained in the term corresponding to v. The test is performed on the virtual term expressed by the additional pointer structure, i.e. one applies Find to all nodes that are reached during the test.





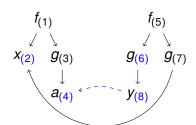


▶ Occur:

Takes as input a variable node u and another node v (both without additional pointers) and performs the occur check, i.e. it tests whether the variable is contained in the term corresponding to v. The test is performed on the virtual term expressed by the additional pointer structure, i.e. one applies Find to all nodes that are reached during the test.

Example

► Occur(2,6)=False



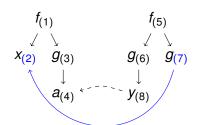




▶ Occur:

Takes as input a variable node u and another node v (both without additional pointers) and performs the occur check, i.e. it tests whether the variable is contained in the term corresponding to v. The test is performed on the virtual term expressed by the additional pointer structure, i.e. one applies Find to all nodes that are reached during the test.

- ► Occur(2,6)=False
- ▶ Occur(2,7)=True







RDA on Term Dags

Input: A pair of nodes k_1 and k_2 in a dag

Output: *True* if the terms corresponding to k_1 and k_2 are unifiable. *False* Otherwise.

Side Effect: A pointer structure which allows to read off an mgu and the unified term.

```
Unify1 (k_1, k_2)

if k_1 = k_2 then return True; /* Trivial */
else

if function\text{-}node(k_2) then

u := k_1; v := k_2

else

u := k_2; v := k_1; /* Orient */
end
```

Procedure Unify1. Recursive descent algorithm on term dags. (Continues on the next slide)



Recursive Descent Algorithm on Term Dags

Procedure Unify1. Recursive descent algorithm on term dags. Continued.

(Continues on the next slide)



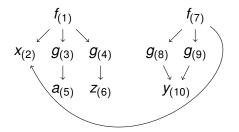
Recursive Descent Algorithm on Term Dags

```
else if function-symbol(u) \neq function-symbol(v)
then
   return False:
                                              /* Symbol clash */
else
   n := arity(function-symbol(u));
   (u_1,\ldots,u_n):=succ-list(u);
   (v_1,\ldots,v_n):=succ-list(v);
   i := 0: bool := True:
   while i < n and bool do
      i := i + 1; bool := Unify1(Find(u_i), Find(v_i));
       /* Decomposition */
   end
   return bool
```

Procedure Unify1. Recursive descent algorithm on term dags. Finished.

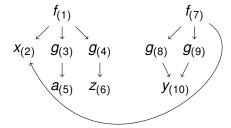


- ▶ Unify f(x, g(a), g(z)) and f(g(y), g(y), x).
- First, create dags.
- Numbers indicate nodes.





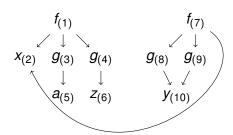






Algorithm run starts with Unify1(1,7) and continues:

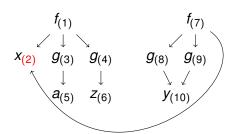
Unify1(Find(2), Find(8))







Unify1(Find(2), Find(8))
Find(2) =
$$(2)$$



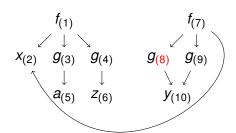




```
Unify1(Find(2), Find(8))

Find(2) = (2)

Find(8) = (8)
```





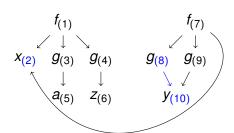


```
Unify1(Find(2), Find(8))

Find(2) = (2)

Find(8) = (8)

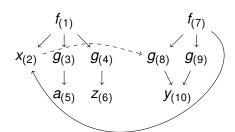
Occur(2,8) = False
```







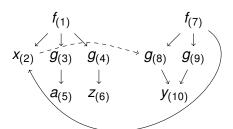
```
Unify1(Find(2), Find(8))
  Find(2) = (2)
  Find(8) = (8)
  Occur(2,8) = False
  Union(2,8)
```







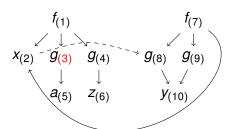
```
Unify1(Find(2), Find(8))
  Find(2) = (2)
  Find(8) = (8)
  Occur(2,8) = False
  Union(2,8)
Unify1(Find(3), Find(9))
```







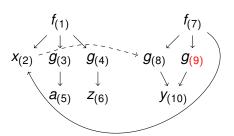
```
\label{eq:unify1} \begin{split} & \text{Unify1}(\text{Find(2), Find(8)}) \\ & \text{Find(2)} = (2) \\ & \text{Find(8)} = (8) \\ & \text{Occur(2,8)} = \textit{False} \\ & \text{Union(2,8)} \\ & \text{Unify1}(\text{Find(3),Find(9)}) \\ & \text{Find(3)} = (3) \end{split}
```







```
Unify1(Find(2), Find(8))
  Find(2) = (2)
  Find(8) = (8)
  Occur(2,8) = False
  Union(2,8)
Unify1(Find(3), Find(9))
  Find(3) = (3)
  Find(9) = (9)
```







```
Unify1(Find(2), Find(8))

Find(2) = (2)

Find(8) = (8)

Occur(2,8) = False

Union(2,8)

Unify1(Find(3), Find(9))

Find(3) = (3)

Find(9) = (9)

Unify1(Find(5), Find(10))
```





```
Unify1(Find(2), Find(8))

Find(2) = (2)

Find(8) = (8)

Occur(2,8) = False

Union(2,8)

Unify1(Find(3), Find(9))

Find(3) = (3)

Find(9) = (9)

Unify1(Find(5), Find(10))

Find(5) = 5
```





```
Unify1(Find(2), Find(8))
  Find(2) = (2)
                                 t_{(1)}
  Find(8) = (8)
  Occur(2,8) = False
  Union(2,8)
Unify1(Find(3), Find(9))
  Find(3) = (3)
  Find(9) = (9)
  Unify1(Find(5), Find(10))
    Find(5) = 5
    Find(10) = 10
```





```
Unify1(Find(2), Find(8))
  Find(2) = (2)
                                 f_{(1)}
  Find(8) = (8)
  Occur(2,8) = False
  Union(2,8)
Unify1(Find(3), Find(9))
  Find(3) = (3)
  Find(9) = (9)
  Unify1(Find(5), Find(10))
    Find(5) = 5
    Find(10) = 10
    orient(10,5)
```





```
Unify1(Find(2), Find(8))
  Find(2) = (2)
                                 f_{(1)}
  Find(8) = (8)
  Occur(2,8) = False
  Union(2,8)
Unify1(Find(3), Find(9))
  Find(3) = (3)
  Find(9) = (9)
  Unify1(Find(5), Find(10))
    Find(5) = 5
    Find(10) = 10
    orient(10,5)
    Occur(10,5) = False
```

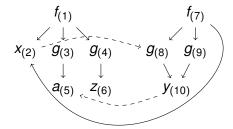




```
Unify1(Find(2), Find(8))
  Find(2) = (2)
                                  f_{(1)}
  Find(8) = (8)
  Occur(2,8) = False
  Union(2,8)
Unify1(Find(3), Find(9))
                                 a_{(5)}
  Find(3) = (3)
  Find(9) = (9)
  Unify1(Find(5), Find(10))
    Find(5) = 5
    Find(10) = 10
    orient(10,5)
    Occur(10,5) = False
    Union(10,5)
```





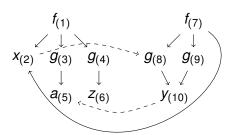






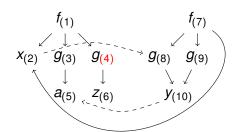
Algorithm run starts with Unify1(1,7) and continues:

Unify1(Find(4), Find(2))









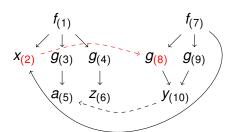




```
Unify1(Find(4),Find(2))

Find(4) = 4

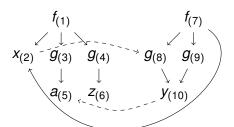
Find(2) = 8
```







```
\begin{split} & \text{Unify1(Find(4),Find(2))} \\ & \text{Find(4)} = 4 \\ & \text{Find(2)} = 8 \\ & \text{Unify1(4,8)} \end{split}
```















```
Unify1(Find(4), Find(2))

Find(4) = 4

Find(2) = 8

Unify1(4,8)

Unify1(Find(6), Find(10))

Find(6) = 6

Find(10) = 5

f_{(1)}

f_{(7)}

f_{(8)}

f_{(7)}

f_{(7)}
```





```
Unify1(Find(4), Find(2))

Find(4) = 4

Find(2) = 8

Unify1(4,8)

Unify1(Find(6), Find(10))

Find(6) = 6

Find(10) = 5

Occur(6,5) = False
```





```
Unify1(Find(4),Find(2))
Find(4) = 4
Find(2) = 8
Unify1(4,8)
Unify1(Find(6),Find(10))
Find(6) = 6
Find(10) = 5
Occur(6,5) = False
Union(6,5)
```





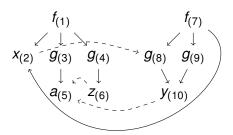
```
Unify1(Find(4),Find(2))
Find(4) = 4
Find(2) = 8
Unify1(4,8)
X_{(2)}
g_{(3)}
g_{(4)}
g_{(8)}
g_{(9)}
Unify1(Find(6),Find(10))
Find(6) = 6
Find(10) = 5
Occur(6,5) = False
Union(6,5)

True
```





RDA on Term Dags. Example 1 (Cont.)



- From the final dag one can read off:
 - ► The unified term f(g(a), g(a), g(a)).
 - ▶ The mgu in triangular form $[x \mapsto g(y); y \mapsto a; z \mapsto a]$.
- ► The algorithm does not create new nodes. Only one extra pointer for each variable node.
- ▶ Needs linear space.
- ► Time is still exponential. See the next example.





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$\begin{array}{cccc} X_{n} & - \rightarrow f & f & - & y_{n} \\ & & & & \downarrow & \downarrow \\ X_{n-1} & \rightarrow f & f & - & y_{n-1} \\ & & & & & \\ X_{1} & - \rightarrow f & f & - & y_{1} \\ & & & & \downarrow & \downarrow \\ & & & & X_{0} & y_{0} \end{array}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \qquad \downarrow$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$\begin{array}{cccc} X_{n} & - \rightarrow f & f & - & y_{n} \\ & & & \downarrow & \downarrow \\ & & & \downarrow & \downarrow \\ X_{n-1} & \rightarrow f & f & - & y_{n-1} \\ & & & & & \\ & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & \\ & & & & \\ & & & \\ & & & & \\ & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & &$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$\begin{array}{ccc}
X_{n} & -- & f & f & -- & y_{n} \\
\downarrow & \downarrow & \downarrow \\
X_{n-1} & -- & f & f & -- & y_{n-1} \\
\vdots & \vdots & \vdots & \vdots & \vdots \\
X_{1} & -- & f & f & -- & y_{1} \\
\downarrow & \downarrow & \downarrow \\
X_{0} & y_{0}
\end{array}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{0} \longrightarrow y_{0}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow$$

$$X_{0} \longrightarrow y_{0}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{0} \longrightarrow y_{0}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \xrightarrow{-} f \qquad f \xleftarrow{-} y_{n}$$

$$\downarrow \downarrow \downarrow \qquad \downarrow \downarrow \downarrow$$

$$X_{n-1} \xrightarrow{-} f \qquad f \xleftarrow{-} y_{n-1}$$

$$\vdots \qquad \vdots \qquad \vdots$$

$$X_{1} \xrightarrow{-} f \qquad f \xleftarrow{-} y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \downarrow$$

$$X_{0} \xrightarrow{-} y_{0}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\vdots \qquad \vdots \qquad \vdots$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{0} \longrightarrow y_{0}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow$$

$$X_{0} \longrightarrow y_{0}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \qquad \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \qquad \downarrow$$

$$X_{0} \longrightarrow y_{0}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \downarrow \qquad \downarrow \downarrow \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\vdots \qquad \vdots \qquad \vdots$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \downarrow$$

$$X_{0} \longrightarrow y_{0}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow$$

$$X_{0} \longrightarrow y_{0}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow$$

$$X_{0} \longrightarrow y_{0}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \qquad \downarrow \qquad \downarrow \qquad \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \qquad \downarrow \qquad \downarrow$$

$$X_{0} \longrightarrow y_{0}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \downarrow \qquad \downarrow \downarrow \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\vdots \qquad \vdots \qquad \vdots$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \downarrow$$

$$X_{0} \longrightarrow y_{0}$$





Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \qquad \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \qquad \downarrow$$

$$X_{0} \longrightarrow y_{0}$$





RDA on Term Dags. Example 2

Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow$$

$$X_{0} \longrightarrow y_{0}$$

Exponential number of recursive calls.





RDA on Term Dags. Example 2

Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow$$

$$X_{0} \longrightarrow y_{0}$$

Exponential number of recursive calls.





RDA on Term Dags. Example 2

Consider again the problem:

$$s = h(x_1, x_2, \dots, x_n, f(y_0, y_0), f(y_1, y_1), \dots, f(y_{n-1}, y_{n-1}), y_n)$$

$$t = h(f(x_0, x_0), f(x_1, x_1), \dots, f(x_{n-1}, x_{n-1}), y_1, y_2, \dots, y_n, x_n)$$

A dag representation of the term bound to x_n and y_n :

$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \qquad \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \qquad \downarrow$$

$$X_{0} \longrightarrow y_{0}$$

Exponential number of recursive calls.





Correctness of RDA for Term Dags

Proof is similar as for the RDA. These two algorithm differ only by the data structure they operate on.



- ▶ Linear space: terms are not duplicated anymore.
- ► Exponential time: Calls Unify1 recursively exponentially often.



- ▶ Linear space: terms are not duplicated anymore.
- ► Exponential time: Calls Unify1 recursively exponentially often.
- Fortunately, with an easy trick one can make the running time quadratic.





- ▶ Linear space: terms are not duplicated anymore.
- ► Exponential time: Calls Unify1 recursively exponentially often.
- Fortunately, with an easy trick one can make the running time quadratic.
- Idea: Keep from revisiting already-solved problems in the graph.





- Linear space: terms are not duplicated anymore.
- ► Exponential time: Calls Unify1 recursively exponentially often.
- Fortunately, with an easy trick one can make the running time quadratic.
- Idea: Keep from revisiting already-solved problems in the graph.
- The algorithm of Corbin and Bidoit:
- J. Corbin and M. Bidoit.
- A rehabilitation of Robinson's unification algorithm. In R. Mason, editor, *Information Processing 83*, pages 909–914. Elsevier Science, 1983.





Outline

Recursive Descent Algorithm is Expensive

Improvement 1: Linear Space, Exponential Time

Improvement 2. Linear Space, Quadratic Time

Improvement 3. Almost Linear Algorithm





Quadratic Algorithm on Term Dags

Input: A pair of nodes k_1 and k_2 in a dag

Output: *True* if the terms corresponding to k_1 and k_2 are

unifiable. False Otherwise.

Side Effect: A pointer structure which allows to read off an mgu and the unified term.

```
Unify2 (k_1, k_2)

if k_1 = k_2 then return True; /* Trivial */
else

if function\text{-}node(k_2) then

u := k_1; v := k_2

else

u := k_2; v := k_1; /* Orient */
end
```

Procedure Unify2. Quadratic Algorithm.

(No difference from Unify1 so far. Continues on the next slide)





Quadratic Algorithm

```
if variable-node(u) then
   if Occurs (u, v);
                                             /* Occur-check */
   then
      return False
   else
      Union(u, v);
                                      /* Variable elimination */
      return True
   end
    Procedure Unify2. Quadratic Algorithm. Continued.
  (No difference from Unify1 so far. Continues on the next slide)
```





Quadratic Algorithm

```
else if function-symbol(u) \neq function-symbol(v)
then
   return False:
                                             /* Symbol clash */
else
   n := arity(function-symbol(u));
   (u_1,\ldots,u_n):=succ-list(u);
   (v_1,\ldots,v_n):=succ-list(v);
   i := 0: bool := True:
   Union(u,v);
   while i < n and bool do
      i := i + 1; bool := Unify2(Find(u_i), Find(v_i));
       /* Decomposition */
   end
   return bool
     Procedure Unify2. Quadratic Algorithm. Finished.
         (The only difference from Unify1 is Union(u,v).)
```









$$X_{n} \longrightarrow f \qquad f \longleftarrow y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \qquad \downarrow$$

$$X_{n-1} \longrightarrow f \qquad f \longleftarrow y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \longrightarrow f \qquad f \longleftarrow y_{1}$$

$$\downarrow \downarrow \qquad \qquad \downarrow$$

$$\chi_{0} \qquad \chi_{0} \qquad \chi_{0}$$





$$X_{n} \xrightarrow{-\rightarrow} f \xrightarrow{-\rightarrow} f \xleftarrow{-} y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \qquad \downarrow$$

$$X_{n-1} \xrightarrow{-\rightarrow} f \qquad f \xleftarrow{-} y_{n-1}$$

$$\downarrow \downarrow \qquad \qquad \downarrow$$

$$X_{1} \xrightarrow{-\rightarrow} f \qquad f \xleftarrow{--} y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \qquad \downarrow$$

$$X_{0} \qquad y_{0}$$





$$X_{n} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \downarrow$$

$$X_{n-1} \xrightarrow{-} f \qquad f \xleftarrow{-} y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \xrightarrow{-} f \qquad f \xleftarrow{-} y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{0} \qquad y_{0}$$





$$X_{n} \xrightarrow{-\rightarrow} f \xrightarrow{\leftarrow} f \xleftarrow{-} y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \downarrow$$

$$X_{n-1} \xrightarrow{\rightarrow} f \xrightarrow{\leftarrow} f \xleftarrow{-} y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \xrightarrow{\rightarrow} f \qquad f \xleftarrow{\leftarrow} y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \qquad \downarrow$$

$$X_{0} \qquad y_{0}$$





$$X_{n} \xrightarrow{--} f \xrightarrow{--} f \xleftarrow{--} y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \downarrow$$

$$X_{n-1} \xrightarrow{--} f \xrightarrow{--} f \xleftarrow{--} y_{n-1}$$

$$\vdots \qquad \vdots \qquad \vdots$$

$$X_{1} \xrightarrow{--} f \qquad f \xleftarrow{--} y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \downarrow$$

$$X_{0} \qquad y_{0}$$



$$X_{n} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{0} \qquad y_{0}$$



$$X_{n} \xrightarrow{--} f \xrightarrow{--} f \xleftarrow{--} y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow \qquad \downarrow$$

$$X_{n-1} \xrightarrow{--} f \xrightarrow{--} f \xleftarrow{--} y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \xrightarrow{--} f \xrightarrow{--} f \xleftarrow{--} y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \qquad \downarrow$$

$$X_{0} \qquad y_{0}$$





$$X_{n} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{0} \xrightarrow{-} y_{0}$$





$$X_{n} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{1}$$

$$\downarrow \qquad \downarrow \qquad \downarrow$$

$$X_{0} \xrightarrow{-} y_{0}$$

$$X_{n} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n-1}$$

$$\vdots \qquad \vdots$$

$$X_{1} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{0} \xrightarrow{-} y_{0}$$





$$X_{n} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{0} \xrightarrow{-} y_{0}$$



$$X_{n} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{n-1} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{n-1}$$

$$\downarrow \qquad \qquad \downarrow$$

$$X_{1} \xrightarrow{-} f \xrightarrow{-} f \xleftarrow{-} y_{1}$$

$$\downarrow \downarrow \qquad \downarrow \downarrow$$

$$X_{0} \xrightarrow{-} y_{0}$$





Properties of the Quadratic Algorithm

- Correctness can be shown in the similar way as for the RDA.
- The algorithm is quadratic in the number of symbols in original terms:
 - ► Each call of Unify2 either returns immediately, or makes one more node unreachable for the Find operation.
 - ▶ Therefore, there can be only linearly many calls of Unify2.
 - ► Quadratic complexity comes from the fact that Occur and Find operations are linear.





Outline

Recursive Descent Algorithm is Expensive

Improvement 1: Linear Space, Exponential Time

Improvement 2. Linear Space, Quadratic Time

Improvement 3. Almost Linear Algorithm





Almost Linear Algorithm

How to eliminate two sources of nonlinearity of Unify2?

- Occur: Just omit the occur check during the execution of the algorithm.
 - Consequence: The data structure may contain cycles.
 - Since the occur-check failures are not detected immediately, at the end an extra check has to be performed to find out whether the generated structure is cyclic or not.
 - Detecting cycles in a directed graph can be done by linear search.
- ▶ Find: Use more efficient union-find algorithm from
 - R. Tarjan.

Efficiency of a good but not linear set union algorithm. *J. ACM*, 22(2):215–225, 1975.





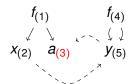
- ► Collapsing-find:
 - Like Find it takes a node k of a dag as input, and follows the additional pointers until the node Find(k) is reached.
 - ▶ In addition, Collapsing-find relocates the pointer of all the nodes reached during this process to Find(k).

$$\begin{array}{cccc}
f_{(1)} & f_{(4)} \\
\downarrow & \downarrow & \downarrow \\
X_{(2)} & a_{(3)} & y_{(5)}
\end{array}$$





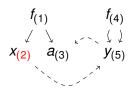
- ► Collapsing-find:
 - Like Find it takes a node k of a dag as input, and follows the additional pointers until the node Find(k) is reached.
 - ▶ In addition, Collapsing-find relocates the pointer of all the nodes reached during this process to Find(k).







- ► Collapsing-find:
 - Like Find it takes a node k of a dag as input, and follows the additional pointers until the node Find(k) is reached.
 - ▶ In addition, Collapsing-find relocates the pointer of all the nodes reached during this process to Find(k).







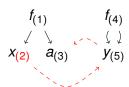
- ► Collapsing-find:
 - Like Find it takes a node k of a dag as input, and follows the additional pointers until the node Find(k) is reached.
 - ▶ In addition, Collapsing-find relocates the pointer of all the nodes reached during this process to Find(k).







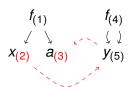
- ► Collapsing-find:
 - Like Find it takes a node k of a dag as input, and follows the additional pointers until the node Find(k) is reached.
 - ▶ In addition, Collapsing-find relocates the pointer of all the nodes reached during this process to Find(k).







- ► Collapsing-find:
 - Like Find it takes a node k of a dag as input, and follows the additional pointers until the node Find(k) is reached.
 - ▶ In addition, Collapsing-find relocates the pointer of all the nodes reached during this process to Find(k).







- ► Collapsing-find:
 - Like Find it takes a node k of a dag as input, and follows the additional pointers until the node Find(k) is reached.
 - ▶ In addition, Collapsing-find relocates the pointer of all the nodes reached during this process to Find(k).





- ▶ Union-with-weight:
 - ► Takes as input a pair of nodes *u*, *v* that do not have additional pointers.
 - ▶ If the set $\{k \mid \text{Find}(k) = u\}$ larger than the set $\{k \mid \text{Find}(k) = v\}$ then it creates an additional pointer from v to u.
 - Otherwise, it creates an additional pointer from u to v.

Weighted union does not apply when we have a variable node and a function node.





One more auxiliary procedure:

- ▶ Not-cyclic:
 - ► Takes a node *k* as input, and tests the graph which can be reached from *k* for cycles.
 - ► The test is performed on the virtual graph expressed by the additional pointer structure, i.e. one first applies

 Collapsing-find to all nodes that are reached during the test.





Input: A pair of nodes k_1 and k_2 in a directed graph.

Output: *True* if k_1 and k_2 correspond unifiable terms. *False* Otherwise.

Side Effect: A pointer structure which allows to read off an mgu and the unified term.

```
Unify3 (k<sub>1</sub>, k<sub>2</sub>)
if Cyclic-unify(k<sub>1</sub>, k<sub>2</sub>) and Not-cyclic(k<sub>1</sub>) then
    return True
else
    return False
end
```

Procedure Unify3. Almost Linear Algorithm. (Continues on the next slide)





```
Cyclic-unify (k_1, k_2)
if k_1 = k_2 then return True;
                                                    /* Trivial */
else
   if function-node(k2) then
      u := k_1; v := k_2
   else
      u := k_2; v := k_1;
                                                    /* Orient */
   end
                 Procedure Cyclic-unify.
                   (Continues on the next slide)
```





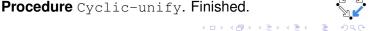
```
if variable-node(u) then
    if variable-node(v) then
        Union-with-weight(u, v)
else
        Union(u, v);    /* No occur-check. Variable elimination */
        return True
    end

Procedure Cyclic-unify.
        (Continues on the next slide)
```





```
else if function-symbol(u) \neq function-symbol(v)
then
   return False:
                                           /* Symbol clash */
else
   n := arity(function-symbol(u));
   (u_1,\ldots,u_n):=succ-list(u);
   (v_1,\ldots,v_n):=succ-list(v);
   i := 0: bool := True:
   Union-with-weight (u,v);
   while i < n and bool do
      i := i + 1:
      bool := Cyclic-unify(Collapsing-find(u_i)
               Collapsing-find(V_i); /* Decomposition */
   end
   return bool
```



The algorithm is very similar to the one described in Gerard Huet's thesis:



G. Huet.

Résolution d'Équations dans des Langages d'ordre $1,2,\ldots,\omega$.

Thèse d'État, Université de Paris VII, 1976.





► The algorithm is almost linear in the number of symbols in original terms:



- The algorithm is almost linear in the number of symbols in original terms:
 - Each call of Cyclic-unify either returns immediately, or makes one more node unreachable for the Collapsing-find operation.





- The algorithm is almost linear in the number of symbols in original terms:
 - Each call of Cyclic-unify either returns immediately, or makes one more node unreachable for the Collapsing-find operation.
 - Therefore, there can be only linearly many calls of Cyclic-unify.



- The algorithm is almost linear in the number of symbols in original terms:
 - Each call of Cyclic-unify either returns immediately, or makes one more node unreachable for the Collapsing-find operation.
 - Therefore, there can be only linearly many calls of Cyclic-unify.
 - ▶ A sequence of n Collapsing—find and Union—with—weight operations can be done in $O(n*\alpha(n))$ time, where α is an extremely slowly growing function (functional inverse of Ackerman's function) never exceeding 5 for practical input.





- The algorithm is almost linear in the number of symbols in original terms:
 - Each call of Cyclic-unify either returns immediately, or makes one more node unreachable for the Collapsing-find operation.
 - Therefore, there can be only linearly many calls of Cyclic-unify.
 - ▶ A sequence of n Collapsing—find and Union—with—weight operations can be done in $O(n*\alpha(n))$ time, where α is an extremely slowly growing function (functional inverse of Ackerman's function) never exceeding 5 for practical input.
 - ► The use of nonoptimal Union can increase the time complexity at most by a summand O(m) where m is the number of different variable nodes.





- The algorithm is almost linear in the number of symbols in original terms:
 - Each call of Cyclic-unify either returns immediately, or makes one more node unreachable for the Collapsing-find operation.
 - Therefore, there can be only linearly many calls of Cyclic-unify.
 - ▶ A sequence of n Collapsing—find and Union—with—weight operations can be done in $O(n*\alpha(n))$ time, where α is an extremely slowly growing function (functional inverse of Ackerman's function) never exceeding 5 for practical input.
 - ► The use of nonoptimal Union can increase the time complexity at most by a summand O(m) where m is the number of different variable nodes.
 - ▶ Therefore, complexity of Cyclic-unify is $O(n * \alpha(n))$.





- The algorithm is almost linear in the number of symbols in original terms:
 - Each call of Cyclic-unify either returns immediately, or makes one more node unreachable for the Collapsing-find operation.
 - Therefore, there can be only linearly many calls of Cyclic-unify.
 - ▶ A sequence of n Collapsing—find and Union—with—weight operations can be done in $O(n*\alpha(n))$ time, where α is an extremely slowly growing function (functional inverse of Ackerman's function) never exceeding 5 for practical input.
 - ► The use of nonoptimal Union can increase the time complexity at most by a summand O(m) where m is the number of different variable nodes.
 - ▶ Therefore, complexity of Cyclic-unify is $O(n * \alpha(n))$.
 - ▶ Complexity of Not-cyclic is linear.





- The algorithm is almost linear in the number of symbols in original terms:
 - Each call of Cyclic-unify either returns immediately, or makes one more node unreachable for the Collapsing-find operation.
 - Therefore, there can be only linearly many calls of Cyclic-unify.
 - ▶ A sequence of n Collapsing—find and Union—with—weight operations can be done in $O(n*\alpha(n))$ time, where α is an extremely slowly growing function (functional inverse of Ackerman's function) never exceeding 5 for practical input.
 - ► The use of nonoptimal Union can increase the time complexity at most by a summand O(m) where m is the number of different variable nodes.
 - ▶ Therefore, complexity of Cyclic-unify is $O(n * \alpha(n))$.
 - ▶ Complexity of Not-cyclic is linear.
 - ▶ Hence, complexity of Unify3 is $O(n * \alpha(n))$.





Summary

- Recursive Descent Algorithm for unification is exponential in time and space.
- Using term dags reduces space complexity to linear.
- Making the union pointer between function nodes before unifying their arguments reduces time complexity to quadratic.
- Using collapsing-find and union-with-weight further reduces time complexity to almost linear.



