Introduction to Unification Theory Equational Unification

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Overview

Motivation

Equational Theories, Reformulations of Notions

Unification Type, Kinds of Unification

Results for Specific Theories

General Results



Outline

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- Unifications algorithms are essential components for deduction systems.
- Simple integration of axioms that describe the properties of equality often leads to an unacceptable increase of search space.
- Proposed solution: To build equational axioms into inference, replacing syntactic unification with equational unification.



Example

Given: Al-theory $\{f(f(x, y), z) \approx f(x, f(y, z)), f(x, x) \approx x\}$. Apply idempotence to the term

 $f(x_0, f(x_1, \ldots, f(x_{n-1}, f(x_n, f(x_0, \ldots, f(x_{n-1}, x_n) \ldots))))))))$



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- ► A human mathematician would use words instead of terms, i.e. would work modulo associativity, and apply idempotence xx = x to the word x₀ ··· x_nx₀ ··· x_n by unifying x with x₀ ··· x_n.

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- To adopt this way of proceeding for a prover, we must replace the syntactic unification algorithm in the resolution step by associative unification.



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- ► Equational theory = E defined by E: The least congruence relation on T(F, V) closed under substitution and containing E i.e., = is the least binary relation on T(F, V) with the properties:
 - $E \subseteq \doteq_E$.
 - Reflexivity: $s \doteq_E s$ for all s.
 - Symmetry: If $s \doteq_E t$ then $t \doteq_E s$ for all s, t.
 - ▶ Transitivity: If $s \doteq_E t$ and $t \doteq_E r$ then $s \doteq_E r$ for all s, t, r.
 - ► Congruence: If $s_1 \doteq_E t_1, \ldots, s_n \doteq_E t_n$ then $f(s_1, \ldots, s_n) \doteq_E f(t_1, \ldots, t_n)$ for all s, t, n and n-ary f.
 - Closure under substitution: If s =_E t then sσ =_E tσ for all s, t, σ.



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Notation, Terminology

- Identities: $s \approx t$.
- ► $s \doteq_E t$: The term *s* is equal modulo *E* to the term *t*.
- E will be called an equational theory as well (abuse of the terminology).
- sig(E): The set of function symbols that occur in *E*.

Example

•
$$C := \{f(x, y) \approx f(y, x)\}$$
: *f* is commutative.
 $sig(C) = f$.

►
$$f(f(a,b),c) \doteq_C f(c,f(b,a)).$$

►
$$AU := \{f(f(x, y), z) \approx f(x, f(y, z)), f(x, e) \approx x, f(e, x) \approx x\}$$
: *f* is associative, *e* is unit.
 $sig(AU) = \{f, e\}$

► $f(a, f(x, f(e, a))) \doteq_{AU} f(f(a, x), a).$



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Notation, Terminology

E-Unification Problem, E-Unifier, E-Unifiability

- *E*: equational theory.
 - \mathcal{F} : set of function symbols.
 - \mathcal{V} : countable set of variables.
- ► E-Unification problem over *F*: a finite set of equations

$$\Gamma = \{ \boldsymbol{s}_1 \doteq^?_E \boldsymbol{t}_1, \ldots, \boldsymbol{s}_n \doteq^?_E \boldsymbol{t}_n \},\$$

where $s_i, t_i \in T(\mathcal{F}, \mathcal{V})$.

• *E*-Unifier of Γ : a substitution σ such that

$$s_1 \sigma \doteq_E t_1 \sigma, \ldots, s_n \sigma \doteq_E t_n \sigma.$$

u_E(Γ): the set of *E*-unifiers of Γ. Γ is *E*-unifiable iff *u_E*(Γ) ≠ Ø.



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E-Unification vs Syntactic Unification

- Syntactic unification: a special case of *E*-unif. with $E = \emptyset$.
- Any syntactic unifier of an E-unification problem Γ is also an E-unifier of Γ.
- For E ≠ Ø, u_E(Γ) may contain a unifier that is not a syntactic unifier.



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Example

- Terms f(a, x) and f(b, y):
 - Not syntactically unifiable.
 - ► Unifiable module commutativity of *f*. *C*-unifier: $\{x \mapsto b, y \mapsto a\}$



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Example

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 - Not syntactically unifiable.
 - ► Unifiable module commutativity of *f*. *C*-unifier: $\{x \mapsto b, y \mapsto a\}$
- Terms f(a, x) and f(y, b):
 - Have the most general syntactic unifier $\{x \mapsto b, y \mapsto a\}$.
 - If f is associative, then u_A({f(a, x) ≐[?]_A f(y, b)}) contains additional A-unifiers, e.g. {x → f(z, b), y → f(a, z)}.



Notions Adapted

Instantiation Quasi-Ordering (Modified)

- E: equational theory. \mathcal{X} : set of variables.
- A substitution σ is more general modulo E on X than ϑ, written σ ≤^X_E ϑ, if there exists η such that xση ≐_E xϑ for all x ∈ X.
- ϑ is called an *E*-instance of σ modulo *E* on \mathcal{X} .
- The relation $\leq_E^{\mathcal{X}}$ is quasi-ordering, called *instantiation quasi-ordering*.
- ► $= \frac{\chi}{E}$ is the equivalence relation corresponding to \leq_{E}^{χ} .



No Single MGU

- When comparing unifiers of Γ , the set \mathcal{X} is *vars*(Γ).
- ► Unifiable *E*-unification problems might not have an mgu.

Example

- f is commutative.
- $\Gamma = \{f(x, y) \doteq_C^? f(a, b)\}$ has two *C*-unifiers:

$$\sigma_1 = \{ x \mapsto a, y \mapsto b \}$$

$$\sigma_2 = \{ x \mapsto b, y \mapsto a \}.$$

- On *vars*(Γ) = {*x*, *y*}, any unifier is equal to either σ_1 or σ_2 .
- σ_1 and σ_2 are not comparable wrt $\leq_C^{\{x,y\}}$.
- Hence, no mgu for Γ.

MCSU vs MGU

In *E*-unification, the role of mgu is taken on by a complete set of *E*-unifiers.

Complete and Minimal Complete Sets of E-Unifiers

- **Γ**: *E*-unification problem over \mathcal{F} .
- $\mathcal{X} = vars(\Gamma)$.
- ► C is a complete set of E-unifiers of Γ iff
 - 1. $C \subseteq u_E(\Gamma)$: C's elements are *E*-unifiers of Γ , and
 - **2**. For each $\vartheta \in u_E(\Gamma)$ there exists $\sigma \in C$ such that $\sigma \leq_E^{\mathcal{X}} \vartheta$.
- C is a minimal complete set of E-unifiers (mcsu_E) of Γ if it is a complete set of E-unifiers of Γ and

3. two distinct elements of C are not comparable wrt $\leq_{E}^{\mathcal{X}}$.

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• σ is an mgu of Γ iff $mcsu_E(\Gamma) = \{\sigma\}$.

MCSU's

- $mcsu_E(\Gamma) = \emptyset$ if Γ is not *E*-unifiable.
- Minimal complete sets of unifiers do not always exist.
- When they exist, they may be infinite.
- When they exist, they are unique up to $= \frac{\chi}{E}$.



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Unification Type of a Problem, Theory.

- E: equational theory.
- Γ: E-unification problem over F.
- Γ has unification type
 - *unitary,* if $mcsu(\Gamma)$ has cardinality at most one,
 - finitary, if mcsu(Γ) has finite cardinality,
 - infinitary, if mcsu(Γ) has infinite cardinality,
 - zero, if mcsu(Γ) does not exist.
- Abbreviation: type unitary 1, finitary ω, infinitary ∞, zero - 0.
- Ordering: $1 < \omega < \infty < 0$.
- ► Unification type of E wrt F: the maximal type of an E-unification problem over F.



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The unification type of an $E\mbox{-equational problem over }\mathcal{F}$ depends both

- ▶ on *E*, and
- ▶ on *F*.

Examples and more details will follow.



Example (Type Unitary)

Syntactic unification.

- The empty equational theory \emptyset : Syntactic unification.
- ► Unitary wrt any *F* because any unifiable syntactic unification problem has an mgu.



Example (Type Finitary)

- ► {f(x, y) =[?]_C f(a, b)} does not have an mgu. C-unification is not unitary.
- Show that it is finitary for any \mathcal{F} :

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 - Let $\Gamma = \{s_1 \doteq_C^? t_1, \dots, s_n \doteq_C^? t_n\}$ be a *C*-unification problem.
 - Consider all possible syntactic unification problems $\Gamma' = \{s'_1 \stackrel{i}{=} {}^{?} t'_1, \dots, s'_n \stackrel{i}{=} {}^{?} t'_n\}$, where $s'_i \stackrel{i}{=}_{C} s_i$ and $t'_i \stackrel{i}{=}_{C} t_i$ for each $1 \le i \le n$.

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 - There are only finitely many such Γ's, because the C-equivalence class for a given term t is finite.



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Commutative unification: $\{f(x, y) \approx f(y, x)\}$

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 - It can be shown that collection of all mgu's of Γ's is a complete set of C-unifiers of Γ. This set if finite.
 - If this set is not minimal (often the case), it can be minimized by removing redundant C-unifiers.



Example (Type Infinitary)

Associative unification: $\{f(f(x, y), z) \approx f(x, f(y, z))\}$.

- ► { $f(x, a) \doteq^{?}_{A} f(a, x)$ } has an infinite *mcsu*: { $\{x \mapsto a\}, \{x \mapsto f(a, a)\}, \{x \mapsto f(a, f(a, a))\}, \ldots$ }
- ► Hence, A-unification can not be unitary or finitary.
- It is not of type zero because any A-unification problem has an mcsu that can be enumerated by the procedure from

G. Plotkin.

Building in equational theories. In B. Meltzer and D. Michie, editors, *Machine Intelligence*, volume 7, pages 73–90. Edinburgh University Press, 1972.

• A-unification is infinitary for any \mathcal{F} .



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Example (Type Zero)

Associative-Idempotent unification:

 $\{f(f(x,y),z)\approx f(x,f(y,z)),f(x,x)\approx x\}.$

- ► {f(x, f(y, x)) =[?]_A f(x, f(z, x))} does not have a minimal complete set of unifiers, see
 - F. Baader.

Unification in idempotent semigroups is of type zero. *J. Automated Reasoning*, 2(3):283–286, 1986.

► Al-unification is of type zero.



Unification Type. Signature Matters

Associative-commutative unification with unit:

 $ACU = \{f(f(x, y), z) \approx f(x, f(y, z)), f(x, y) \approx f(y, x), f(x, e) \approx x\}.$

- Any ACU problem built using only f and variables has an mgu (i.e. is unitary).
- ► There are ACU problems that contain function symbols other than f and e, which are finitary, not unitary. For instance, mcsu({f(x, y) =[?]_{ACU} f(a, b)}) consists of four unifiers (which ones?).

Kinds of *E*-unification.



Kinds of E-Unification

One may distinguish three kinds of *E*-unification problems, depending on the function symbols that are allowed to occur in them.

E-Unification Problems: Elementary, with Constants, General.

- E: an equational Theory.
 - Γ : an *E*-unification problem over \mathcal{F} .
- **Γ** is an elementary *E*-unification problem iff $\mathcal{F} = sig(E)$.
- Γ is an *E*-unification problem with constants iff *F* \ sig(E) consists of constants.
- ► Γ is a general *E*-unification problem iff *F* \ sig(E) may contain arbitrary function symbols.



Unification Types of Theories wrt Kinds

- ► Unification type of *E* wrt elementary unification: Maximal unification type of *E* wrt all *F* such that *F* = sig(*E*).
- ► Unification type of *E* wrt unification with constants: Maximal unification type of *E* wrt all *F* such that *F* \ sig(*E*) is a set of constants.
- ► Unification type of *E* wrt general unification: Maximal unification type of *E* wrt all *F* such that *F* \ sig(*E*) is a set of arbitrary function symbols.



Unification Types of Theories wrt Kinds

The same equational theory can have different unification types for different kinds. Examples:

- ACU (Abelian monoids): Unitary wrt elementary unification, finitary wrt unification with constants and general unification.
- AG (Abelian groups): Unitary wrt elementary unification and unification with constants, finitary wrt general unification.



Decision procedure for an equational theory E (wrt F): An algorithm that for each E-unification problem Γ (wrt F) returns success if Γ is E-unifiable, and failure otherwise.



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- (Minimal) E-unification procedure: A procedure that enumerates a possible infinite (minimal) complete set of E-unifiers.



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- E-unification algorithm yields a decision procedure for E.
- (Minimal) E-unification procedure: A procedure that enumerates a possible infinite (minimal) complete set of E-unifiers.
- E-unification procedure does not yield a decision procedure for E.



Decidability wrt Kinds

Decidability of an equational theory might depend on the kinds of *E*-unification.

- There exists an equational theory for which elementary unification is decidable, but unification with constants is undecidable:
 - H.-J. Bürckert.

Some relationships between unification, restricted unification, and matching.

In J. Siekmann, editor, *Proc. 8th Int. Conference on Automated Deduction*, volume 230 of *LNCS*. Springer, 1986.



Three Main Questions in Unification Theory

For a given E, unification theory is mainly concerned with finding answers to the following three questions:

Decidability: Is it decidable whether an *E*-unification problem is solvable? If yes, what is the complexity of this decision problem?

Unification type: What is the unification type of the theory *E*? Unification algorithm: How can we obtain an (efficient) *E*-unification algorithm, or a (preferably minimal) *E*-unification procedure?

The answers depend on whether we consider elementary unification, unification with constants, or general unification.



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General unification:

Theory	Decidability	Туре	Algorithm/Procedure
Ø	Yes	1	Yes
A	Yes	∞	Yes
С	Yes	ω	Yes
1	Yes	ω	Yes
AC	Yes	ω	Yes
AI	Yes	0	?
CI	Yes	ω	Yes
ACI	Yes	ω	Yes
AU	Yes	∞	Yes
AG	Yes	ω	Yes
CRU	No	? (∞ or 0)	?

CRU - Commutative ring with unit



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C-unification algorithm U_C can be obtained from the inference system U by adding the C-Decomposition rule:

C-Decomposition: $\{f(s_1, s_2) \doteq_C^? f(t_1, t_2)\} \cup P'; S \Longrightarrow$ $\{s_1 \doteq_C^? t_2, s_2 \doteq_C^? t_1\} \cup P'; S,$ if *f* is commutative.

 C-Decomposition and Decomposition transform the same system in different ways.



In order to *C*-unify *s* and *t*:

- 1. Create an initial system $\{s \doteq_{C}^{?} t\}; \emptyset$.
- 2. Apply successively rules from U_C , building a complete tree of derivations. **C-Decomposition** and **Decomposition** rules have to be applied concurrently and form branching points in the derivation tree.



$$\{g(f(x,y),z) \doteq^?_C g(f(f(a,b),f(b,a))),c)\}; \emptyset$$



$$\{g(f(x,y),z) \doteq^{?}_{C} g(f(f(a,b),f(b,a))),c)\}; \emptyset$$

$$\downarrow$$

$$\{f(x,y) \doteq^{?}_{C} f(f(a,b),f(b,a)), z \doteq^{?}_{C} c\}; \emptyset$$











C-unify g(f(x, y), z) and g(f(f(a, b), f(b, a)), c), commutative f.

$$\{g(f(x,y),z) \doteq_{C}^{?} g(f(f(a,b),f(b,a))),c)\}; \emptyset \\ \downarrow \\ \{f(x,y) \doteq_{C}^{?} f(f(a,b),f(b,a)), z \doteq_{C}^{?} c\}; \emptyset \\ \{x \doteq_{C}^{?} f(a,b), y \doteq_{C}^{?} f(b,a), z \doteq_{C}^{?} c\}; \emptyset \\ \{x \doteq_{C}^{?} f(b,a), z \doteq_{C}^{?} c\}; \{x \doteq f(a,b)\} \\ \{y \doteq_{C}^{?} f(b,a), z \doteq_{C}^{?} c\}; \{x \doteq f(a,b)\} \\ \downarrow \\ \{y \doteq_{C}^{?} c\}; \{x \doteq f(a,b), y \doteq f(b,a)\} \\ \downarrow \\ \{z \doteq_{C}^{?} c\}; \{x \doteq f(a,b), y \doteq f(b,a)\} \\ \downarrow \\ \emptyset; \{x \doteq f(a,b), y \doteq f(b,a), z \doteq c\}$$



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C-unify g(f(x, y), z) and g(f(f(a, b), f(b, a)), c), commutative f.

$$\{g(f(x,y),z) \doteq_{C}^{?} g(f(f(a,b),f(b,a))),c)\}; \emptyset \\ \downarrow \\ \{f(x,y) \doteq_{C}^{?} f(f(a,b),f(b,a)), z \doteq_{C}^{?} c\}; \emptyset \\ \{x \doteq_{C}^{?} f(a,b), y \doteq_{C}^{?} f(b,a), z \doteq_{C}^{?} c\}; \emptyset \\ \{x \doteq_{C}^{?} f(a,b), y \doteq_{C}^{?} f(b,a), z \doteq_{C}^{?} c\}; \emptyset \\ \{y \doteq_{C}^{?} f(b,a), z \doteq_{C}^{?} c\}; \{x \doteq f(a,b)\} \\ \{y \doteq_{C}^{?} f(b,a), z \doteq_{C}^{?} c\}; \{x \doteq f(a,b)\} \\ \downarrow \\ \{z \doteq_{C}^{?} c\}; \{x \doteq f(a,b), y \doteq f(b,a)\} \\ \{z \doteq_{C}^{?} c\}; \{x \doteq f(a,b), y \doteq f(b,a), z \doteq_{C}^{?} c\}; \{x \doteq f(b,a), y \doteq f(a,b)\} \\ \downarrow \\ \emptyset; \{x \doteq f(a,b), y \doteq f(b,a), z \doteq_{C}^{?} \}$$

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C-unify g(f(x, y), z) and g(f(f(a, b), f(b, a)), c), commutative f.

$$\{g(f(x, y), z) \doteq_{C}^{?} g(f(f(a, b), f(b, a))), c)\}; \emptyset \downarrow \\ \{f(x, y) \doteq_{C}^{?} f(f(a, b), f(b, a)), z \doteq_{C}^{?} c\}; \emptyset \\ \{x \doteq_{C}^{?} f(a, b), y \doteq_{C}^{?} f(b, a), z \doteq_{C}^{?} c\}; \emptyset \\ \{x \doteq_{C}^{?} f(a, b), y \doteq_{C}^{?} f(b, a), z \doteq_{C}^{?} c\}; \emptyset \\ \{y \doteq_{C}^{?} f(b, a), z \doteq_{C}^{?} c\}; \{x \doteq f(a, b)\} \\ \{y \doteq_{C}^{?} f(b, a), z \doteq_{C}^{?} c\}; \{x \doteq f(a, b)\} \\ \{y \doteq_{C}^{?} c\}; \{x \doteq f(a, b), y \doteq f(b, a)\} \\ \{z \doteq_{C}^{?} c\}; \{x \doteq f(a, b), y \doteq f(b, a)\} \\ \{z \doteq_{C}^{?} c\}; \{x \doteq f(a, b), y \doteq f(b, a), z \doteq_{C}^{?} c\}; \{x \doteq f(a, b), z = c\} \\ \emptyset; \{x \doteq f(a, b), y \doteq f(b, a), z \doteq_{C}^{?} b\}; \{x \doteq f(b, a), y \doteq f(a, b), z = c\}$$

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C-unify g(f(x, y), z) and g(f(f(a, b), f(b, a)), c), commutative f.

 $\{\{x \mapsto f(b, a), y \mapsto f(a, b), z \mapsto c\}, \{x \mapsto f(a, b), y \mapsto f(b, a), z \mapsto c\}\}$ Not minimal.

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 $ACU = \{f(f(x, y), z) \approx f(x, f(y, z)), f(x, y) \approx f(y, x), f(x, e) \approx e\}$

Elementary ACU-unification problem:

$$\Gamma = \{f(x, f(x, y)) \doteq_{ACU}^{?} f(z, f(z, z))\}$$

Solving idea:

1. Associate with the equation in Γ a homogeneous linear Diophantine equation. The Diophantine equation states that the number of new variables introduced by a unifier σ in both sides of $\Gamma \sigma$ must be the same:

$$2x + y = 3z$$
.

(Continues on the next slide.)



Solving (Cont.):

2. Solve 2x + y = 3z over nonnegative integers. Three minimal solutions:

$$x = 1, y = 1, z = 1$$

 $x = 0, y = 3, z = 1$
 $x = 3, y = 0, z = 2$

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Any other solution of the equation can be obtained as a nonnegative linear combination of these three solutions. (Continues on the next slide.)

Solving (Cont.):

3. Introduce new variables v_1 , v_2 , v_3 for each solution of the Diophantine equation:

	X	у	Ζ
<i>V</i> ₁	1	1	1
<i>V</i> ₂	0	3	1
V ₃	3	0	2

4. Each row corresponds to a unifier of Γ :

$$\sigma_1 = \{ x \mapsto v_1, y \mapsto v_1, z \mapsto v_1 \}$$

$$\sigma_2 = \{ x \mapsto e, y \mapsto f(v_2, f(v_2, v_2)), z \mapsto v_2 \}$$

$$\sigma_3 = \{ x \mapsto f(v_3, f(v_3, v_3)), y \mapsto e, z \mapsto f(v_3, v_3) \}$$

However, none of them is an mgu.



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Solving (Cont.):

5. To obtain an mgu, we should combine all three solutions:

		X	у	Ζ
	<i>V</i> ₁	1	1	1
	<i>V</i> 2	0	3	1
_	V ₃	3	0	2

Looking at columns: They state that the mgu we are looking for should have

- in the binding for x one v_1 , zero v_2 , and three v_3 's,
- in the binding for y one v_1 , three v_2 's, and zero v_3 ,
- in the binding for z one v₁, one v₂, and two v₃'s
- 6. Hence, we can construct the mgu:

 $\sigma = \{ x \mapsto f(v_1, f(v_3, f(v_3, v_3)), y \mapsto f(v_1, f(v_2, f(v_2, v_2)), z \mapsto f(v_1, f(v_2, f(v_3, v_3))) \}$



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Exercise.

Verify that the unifiers σ_1 , σ_2 and σ_3 are instances of σ .



Example

- Equational theory: $E = \{f(e, x) \approx x, g(f(x, y)) \approx g(y)\}.$
- *E*-unification problem: $\Gamma = \{g(x) \doteq_E^? g(e)\}.$



Example

- Equational theory: $E = \{f(e, x) \approx x, g(f(x, y)) \approx g(y)\}.$
- *E*-unification problem: $\Gamma = \{g(x) \doteq_E^? g(e)\}.$
- Complete (why?) set of solutions:

$$\sigma_0 = \{ x \mapsto e \}$$

$$\sigma_1 = \{ x \mapsto f(x_0, e) \}$$

$$\sigma_2 = \{ x \mapsto f(x_1, f(x_0, e)) \}$$

...

$$\sigma_n = \{ x \mapsto f(x_{n-1}, x\sigma_{n-1}) \}$$



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Example

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Complete (why?) set of solutions:

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$$\sigma_2 = \{ x \mapsto f(x_1, f(x_0, e)) \}$$

$$\dots$$

$$\sigma_n = \{ x \mapsto f(x_{n-1}, x \sigma_{n-1}) \}$$

► No *mcsu*. $\sigma_i = {x \atop E} \sigma_{i+1} \{ x_i \mapsto e \}$. $\sigma_i \not\leq {x \atop E} \sigma_j$ for i > j. Infinite descending chain: $\sigma_0 >_E^{\{x\}} \sigma_1 >_E^{\{x\}} \sigma_2 >_E^{\{x\}} \cdots$



Example (Cont.) Why does $\sigma_0 >_E^{\{x\}} \sigma_1 >_E^{\{x\}} \sigma_2 >_E^{\{x\}} \cdots$ imply that there is no *mcsu*?

• Let
$$S = \{\sigma_0, \sigma_1, ...\}.$$



Example (Cont.) Why does $\sigma_0 >_E^{\{x\}} \sigma_1 >_E^{\{x\}} \sigma_2 >_E^{\{x\}} \cdots$ imply that there is no *mcsu*?

- Let $S = \{\sigma_0, \sigma_1, \ldots\}.$
- Let S' be an arbitrary complete set of unifiers of Γ .



Example (Cont.) Why does $\sigma_0 >_F^{\{x\}} \sigma_1 >_F^{\{x\}} \sigma_2 >_F^{\{x\}} \cdots$ imply that there is no

Why does $\sigma_0 \geq_E^{\alpha_1} \sigma_1 \geq_E^{\alpha_2} \sigma_2 \geq_E^{\alpha_3} \cdots$ imply that there is r *mcsu*?

- Let $S = \{\sigma_0, \sigma_1, \ldots\}.$
- Let S' be an arbitrary complete set of unifiers of Γ .
- Since S is complete, for any θ ∈ S' there exists σ_i ∈ S such that σ_i ≤^{x}_E θ.



Example (Cont.)

Why does $\sigma_0 >_E^{\{x\}} \sigma_1 >_E^{\{x\}} \sigma_2 >_E^{\{x\}} \cdots$ imply that there is no *mcsu*?

- Let $S = \{\sigma_0, \sigma_1, \ldots\}.$
- Let S' be an arbitrary complete set of unifiers of Γ .
- Since S is complete, for any θ ∈ S' there exists σ_i ∈ S such that σ_i ≤^{x}_F θ.
- Since $\sigma_{i+1} \leq_E^{\{x\}} \sigma_i$, we get $\sigma_{i+1} \leq_E^{\{x\}} \vartheta$.

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Example (Cont.)

Why does $\sigma_0 >_E^{\{x\}} \sigma_1 >_E^{\{x\}} \sigma_2 >_E^{\{x\}} \cdots$ imply that there is no *mcsu*?

- Let $S = \{\sigma_0, \sigma_1, \ldots\}.$
- Let S' be an arbitrary complete set of unifiers of Γ .
- Since S is complete, for any θ ∈ S' there exists σ_i ∈ S such that σ_i ≤^{x}_F θ.
- Since $\sigma_{i+1} \leq_E^{\{x\}} \sigma_i$, we get $\sigma_{i+1} \leq_E^{\{x\}} \vartheta$.
- On the other hand, since S' is complete, there exists η ∈ S' such that η ≤^{x}_E σ_{i+1}.



Example (Cont.)

Why does $\sigma_0 >_E^{\{x\}} \sigma_1 >_E^{\{x\}} \sigma_2 >_E^{\{x\}} \cdots$ imply that there is no *mcsu*?

- Let $S = \{\sigma_0, \sigma_1, \ldots\}.$
- Let S' be an arbitrary complete set of unifiers of Γ .
- Since S is complete, for any θ ∈ S' there exists σ_i ∈ S such that σ_i ≤^{x}_F θ.
- Since $\sigma_{i+1} <_{E}^{\{x\}} \sigma_i$, we get $\sigma_{i+1} <_{E}^{\{x\}} \vartheta$.
- ▶ On the other hand, since *S'* is complete, there exists $\eta \in S'$ such that $\eta \leq_{E}^{\{x\}} \sigma_{i+1}$.
- Hence, $\eta <_E^{\{x\}} \vartheta$ which implies that S' is not minimal.



For each specific equational theory separately studying

- decidability,
- unification type,
- unification algorithm/procedure.

Can one study these problems for bigger classes of equational theories?

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Outline

Motivation

Equational Theories, Reformulations of Notions

Unification Type, Kinds of Unification

Results for Specific Theories

General Results



In general, unification modulo equational theories

- is undecidable,
- unification type of a given theory is undecidable,
- admits a complete unification procedure (Gallier & Snyder, called an universal *E*-unification procedure).



General Results

Universal *E*-unification procedure U_E .

Rules:

Trivial, Orient, Decomposition, Variable Elimination from U, plus

Lazy Paramodulation:

$$\{e[u]\} \cup P'; S \Longrightarrow \{I \doteq u, e[r]\} \cup P'; S,$$

for a fresh variant of the identity $I \approx r$ from $E \cup E^{-1}$, where

- e[u] is an equation where the term u occurs,
- *u* is not a variable,
- if I is not a variable, then the top symbol of I and u are the same.



Universal E-unification procedure. Control.

In order to solve a unification problem Γ modulo a given *E*:

- Create an initial system Γ ; Ø.
- Apply successively rules from U_E, building a complete tree of derivations.
- No other inference rule may be applied to the equation *l* =[?] *u* that is generated by the Lazy Paramodulation rule before it is subjected to a Decomposition step.



General Results

Universal *E*-unification procedure.

Example

 $E = \{f(a, b) \approx a, a \approx b\}.$

Unification problem: $\{f(x, x) \doteq_{E}^{?} x\}$.

Computing a unifier $\{x \mapsto a\}$ by the universal procedure:

$$\{f(x,x) \doteq_E^? x\}; \emptyset \Longrightarrow_{LP} \{f(a,b) \doteq_E^? f(x,x), a \doteq_E^? x\}; \emptyset \Longrightarrow_D \{a \doteq_E^? x, b \doteq_E^? x, a \doteq_E^? x\}; \emptyset \Longrightarrow_O \{x \doteq_E^? a, b \doteq_E^? x, a \doteq_E^? x\}; \emptyset \Longrightarrow_S \{b \doteq_E^? a, a \doteq_E^? a\}; \{x \doteq a\} \Longrightarrow_{LP} \{a \doteq_E^? a, b \doteq_E^? b, a \doteq_E^? a\}; \{x \doteq a\} \Longrightarrow_T^+ \emptyset; \{x \doteq a\}$$



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Pros and cons of the universal procedure:

- ▶ Pros: Is sound and complete. Can be used for any *E*.
- Cons: Very inefficient. Usually does not yield a decision procedure or a (minimal) *E*-unification algorithm even for unitary or finitary theories with decidable unification.



More useful results can be obtained by imposing additional restrictions on equational theories:

- Syntactic approaches: Restricting syntactic form of the identities defining equational theories.
- Semantic approaches: Depend on properties of the free algebras defined by the equational theory.

