# Introduction to Unification Theory Solving Systems of Linear Diophantine Equations

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#### **ACU-Unification**

- ▶ We saw an example how to solve ACU-unification problem.
- Reduction to systems of linear Diophantine equations (LDEs) over natural numbers.



# Elementary ACU-Unification

Elementary ACU-unification problem

$$\{f(x, f(x, y)) \stackrel{?}{=}_{ACU}^? f(z, f(z, z))\}$$

reduces to homogeneous linear Diophantine equation

$$2x + y = 3z.$$

- Each equation in the unification problem gives rise to one linear Diophantine equation.
- ▶ A most general ACU-unifier is obtained by combining all the unifiers corresponding to the minimal solutions of the system of LDEs.



# Elementary ACU-Unification

- $\Gamma = \{ f(x, f(x, y)) \stackrel{?}{=}_{ACU}^{?} f(z, f(z, z)) \} \text{ and } S = \{ 2x + y = 3z \}.$
- ▶ S has three minimal solutions: (1, 1, 1), (0, 3, 1), (3, 0, 2).
- ▶ Three unifiers of  $\Gamma$ :

$$\sigma_{1} = \{x \mapsto v_{1}, y \mapsto v_{1}, z \mapsto v_{1}\} 
\sigma_{2} = \{x \mapsto e, y \mapsto f(v_{2}, f(v_{2}, v_{2})), z \mapsto v_{2}\} 
\sigma_{3} = \{x \mapsto f(v_{3}, f(v_{3}, v_{3})), y \mapsto e, z \mapsto f(v_{3}, v_{3})\}$$

▶ A most general unifier of  $\Gamma$ :

$$\sigma = \{x \mapsto f(v_1, f(v_3, f(v_3, v_3))), y \mapsto f(v_1, f(v_2, f(v_2, v_2))), z \mapsto f(v_1, f(v_2, f(v_3, v_3)))\}$$





## **ACU-Unification with constants**

ACU-unification problem with constants

$$\Gamma = \{ f(x, f(x, y)) \stackrel{?}{=}_{ACU}^? f(a, f(z, f(z, z))) \}$$

reduces to inhomogeneous linear Diophantine equation

$$S = \{2x + y = 3z + 1\}.$$

▶ The minimal nontrivial natural solutions of S are (0,1,0) and (2,0,1).

#### ACU-Unification with constants

ACU-unification problem with constants

$$\Gamma = \{ f(x, f(x, y)) \stackrel{?}{=}_{ACU}^? f(a, f(z, f(z, z))) \}$$

reduces to inhomogeneous linear Diophantine equation

$$S = \{2x + y = 3z + 1\}.$$

- ▶ Every natural solution of S is obtained by as the sum of one of the minimal solution and a solution of the corresponding homogeneous LDE 2x + y = 3z.
- One element of the minimal complete set of unifiers of  $\Gamma$  is obtained from the combination of one minimal solution of S with the set of all minimal solutions of 2x + y = 3z.





#### ACU-Unification with constants

ACU-unification problem with constants

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reduces to inhomogeneous linear Diophantine equation

$$S = \{2x + y = 3z + 1\}.$$

▶ The minimal complete set of unifiers of  $\Gamma$  is  $\{\sigma_1, \sigma_2\}$ , where

$$\sigma_{1} = \{x \mapsto f(v_{1}, f(v_{3}, f(v_{3}, v_{3}))), 
y \mapsto f(a, f(v_{1}, f(v_{2}, f(v_{2}, v_{2}))), 
z \mapsto f(v_{1}, f(v_{2}, f(v_{3}, v_{3})))\} 
\sigma_{2} = \{x \mapsto f(a, f(a, f(v_{1}, f(v_{3}, f(v_{3}, v_{3}))))), 
y \mapsto f(v_{1}, f(v_{2}, f(v_{2}, v_{2})), 
z \mapsto f(a, f(v_{1}, f(v_{2}, f(v_{3}, v_{3}))))\}$$





# How to Solve Systems of LDEs over Naturals?

#### Contejean-Devie Algorithm:



Evelyne Contejean and Hervé Devie.

An Efficient Incremental Algorithm for Solving Systems of Linear Diophantine Equations.

Information and Computation 113(1): 143-172 (1994).

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Generalizes Fortenbacher's Algorithm for solving a single equation:



Michael Clausen and Albrecht Fortenbacher.

Efficient Solution of Linear Diophantine Equations.

J. Symbolic Computation 8(1,2): 201–216 (1989).



Homogeneous linear Diophantine system with m equations and n variables:

$$\begin{cases} a_{11}x_1 + \dots + a_{1n}x_n = 0 \\ \vdots & \vdots & \vdots \\ a_{m1}x_1 + \dots + a_{mn}x_n = 0 \end{cases}$$

- $ightharpoonup a_{ij}$ 's are integers.
- ▶ Looking for nontrivial natural solutions.



#### Example

$$\begin{cases} -x_1 + x_2 + 2x_3 - 3x_4 = 0 \\ -x_1 + 3x_2 - 2x_3 - x_4 = 0 \end{cases}$$

#### Nontrivial solutions:

- $s_1 = (0, 1, 1, 1)$
- $s_2 = (4, 2, 1, 0)$
- $s_3 = (0, 2, 2, 2)$
- $s_4 = (8,4,2,0)$
- $s_5 = (4, 3, 2, 1)$
- $s_6 = (8, 5, 3, 1)$
- ▶ ..



## Example

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#### Nontrivial solutions:

- $s_1 = (0, 1, 1, 1)$
- $s_2 = (4, 2, 1, 0)$
- $ightharpoonup s_3 = (0, 2, 2, 2) = 2s_1$
- $\bullet$   $s_4 = (8, 4, 2, 0) = 2s_2$
- $s_5 = (4,3,2,1) = s_1 + s_2$
- ▶ ...





Homogeneous linear Diophantine system with m equations and n variables:

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- Looking for a basis in the set of nontrivial natural solutions.



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- $ightharpoonup a_{ij}$ 's are integers.
- Looking for a basis in the set of nontrivial natural solutions.
- Does it exist?





The basis in the set S of nontrivial natural solutions of a homogeneous LDS is the set of  $\gg$ -minimal elements S.

≫ is the ordering on tuples of natural numbers:

$$(x_1,\ldots,x_n)\gg(y_1,\ldots,y_n)$$

if and only if

- $x_i \ge y_i$  for all  $1 \le i \le n$  and
- $x_i > y_i$  for some  $1 \le i \le n.$





#### Matrix Form

Homogeneous linear Diophantine system with m equations and n variables:

$$Ax_{\downarrow} = 0_{\downarrow},$$

where

$$A := \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & & \vdots \\ a_{m1} & \cdots & a_{mn} \end{pmatrix} \quad x_{\downarrow} := \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \quad 0_{\downarrow} := \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix}$$

## Matrix Form

▶ Canonical basis in  $\mathbb{N}^n$ :  $(e_{1\downarrow}, \dots, e_{n\downarrow})$ .

$$e_{j\downarrow} = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \text{ with } 1 \text{ in } j\text{'s row.}$$

▶ Then  $Ax_{\downarrow} = x_1 Ae_{1\downarrow} + \cdots + x_n Ae_{n\downarrow}$ .



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- ▶ Then  $Ax_{\downarrow} = x_1 Ae_{1\downarrow} + \cdots + x_n Ae_{n\downarrow}$ .
- a: The linear mapping associated to A.
- ▶ Then  $a(x_{\downarrow}) = x_1 a(e_{1\downarrow}) + \cdots + x_n a(e_{n\downarrow}).$



## Single Equation: Idea

- Search minimal solutions starting from the elements in the canonical basis of  $\mathbb{N}^n$ .
- ▶ Suppose the current vector  $v_{\downarrow}$  is not a solution.
- It can be nondeterministically increased, component by component, until it becomes a solution or greater than a solution.
- ► To decrease the search space, the following restrictions can be imposed:
  - ▶ If  $a(v_{\downarrow}) > 0$ , then increase by one some  $v_j$  with  $a_j < 0$ .
  - ▶ If  $a(v_{\downarrow}) < 0$ , then increase by one some  $v_j$  with  $a_j > 0$ .





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  - ▶ If  $a(v_{\downarrow}) < 0$ , then increase by one some  $v_j$  with  $a_j > 0$ .
  - ▶ (If  $a(v_{\downarrow})a(e_{j_{\downarrow}}) < 0$  for some j, increase  $v_j$  by one.)





## Single Equation: Geometric Interpretation of the Idea

- ▶ Fortenbacher's condition If  $a(v_{\downarrow})a(e_{j_{\perp}}) < 0$  for some j, increase  $v_j$  by one.
- ▶ Increasing  $v_j$  by one:  $a(v_{\downarrow} + e_{j_{\downarrow}}) = a(v_{\downarrow}) + a(e_{j_{\downarrow}})$ .
- ▶ Going to the "right direction", towards the origin.

O	$a(v_{\downarrow})$		Forbidden
•		$a(e_{j\downarrow})$	direction







Case m=1: Single homogeneous LDE  $a_1x_1+\cdots+a_nx_n=0$ . Fortenbacher's algorithm:

▶ Start with the pair P, M of the set of potential solutions  $P = \{e_{1\downarrow}, \dots, e_{n\downarrow}\}$  and the set of minimal nontrivial solutions  $M = \emptyset$ .



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- Apply repeatedly the rules:
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  - $\begin{array}{l} \text{2. } \{v_{\downarrow}\} \cup P', M \Longrightarrow P', \{v_{\downarrow}\} \cup M, \\ \text{if } a(v_{\downarrow}) = 0 \text{ and rule } 1 \text{ is not applicable.} \end{array}$





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  - 3.  $P, M \Longrightarrow \{v_{\downarrow} + e_{j_{\downarrow}} \mid v_{\downarrow} \in P, \ a(v_{\downarrow})a(e_{j_{\downarrow}}) < 0, \ j \in 1..n\}, M$ , if rules 1 and 2 are not applicable.





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- ▶ If  $\emptyset$ , M is reached, return M.





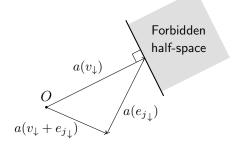
## System of Equations: Idea

- General case: System of homogeneous LDEs.
- $\bullet$   $a(x_{\downarrow}) = 0_{\downarrow}$ .
- Generalizing Fortenbacher's idea:
  - Search minimal solutions starting from the elements in the canonical basis of  $\mathbb{N}^n$ .
  - ▶ Suppose the current vector  $v_{\downarrow}$  is not a solution.
  - It can be nondeterministically increased, component by component, until it becomes a solution or greater than a solution.
  - ► To decrease the search space, increase only those components that lead to the "right direction".



## System of Equations: How to Restrict

- "Right direction": Towards the origin.
- ▶ If  $a(v_{\downarrow}) \neq 0_{\downarrow}$ , then do  $a(v_{\downarrow} + e_{j_{\downarrow}}) = a(v_{\downarrow}) + a(e_{j_{\downarrow}})$ .
- ▶  $a(v_{\downarrow}) + a(e_{j|})$  should lie in the half-space containing O.
- ▶ Contejean-Devie condition: If  $a(v_{\downarrow}) \cdot a(e_{j_{\downarrow}}) < 0$  for some j, increase  $v_j$  by one. (· is the scalar product.)

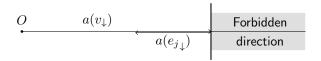




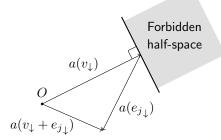


## How to Restrict: Comparison

Fortenbacher's condition If  $a(v_{\downarrow})a(e_{j_{\downarrow}}) < 0$  for some j, increase  $v_{j}$  by one.



► Contejean-Devie condition If  $a(v_{\downarrow}) \cdot a(e_{j_{\perp}}) < 0$  for some j, increase  $v_j$  by one.







# System of Equations: Algorithm

System of homogeneous LDEs:  $a(x_{\downarrow}) = 0_{\downarrow}$ . Contejean-Devie algorithm:

- ► Start with the pair *P*, *M* where
  - ▶  $P = \{e_{1\downarrow}, \dots, e_{n\downarrow}\}$  is the set of potential solutions,
  - ▶  $M = \emptyset$  is the set of minimal nontrivial solutions.
- Apply repeatedly the rules:
  - $1. \ \{v_{\downarrow}\} \cup P', M \Longrightarrow P', M,$  if  $v_{\downarrow} \gg u_{\downarrow}$  for some  $u_{\downarrow} \in M$ .
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- ▶ If  $\emptyset$ , M is reached, return M.





$$\begin{cases} - & x_1 + x_2 + 2x_3 - 3x_4 = 0 \\ - & x_1 + 3x_2 - 2x_3 - x_4 = 0 \end{cases}$$

$$e_{1\downarrow} = (1, 0, 0, 0)^T$$
  $e_{2\downarrow} = (0, 1, 0, 0)^T$   
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- $\begin{array}{ll} 1. & \{v_{\downarrow}\} \cup P', M \Longrightarrow P', M, \\ & \text{if } v_{\downarrow} \gg u_{\downarrow} \text{ for some } u_{\downarrow} \in M. \end{array}$
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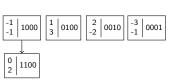




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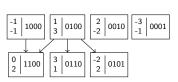




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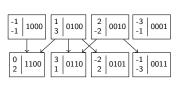




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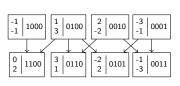




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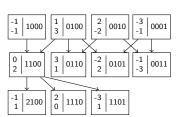




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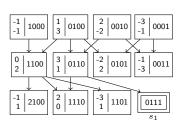




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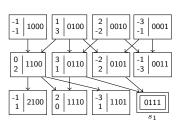




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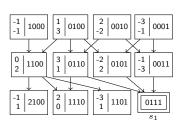




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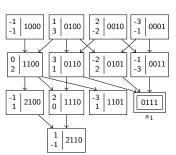




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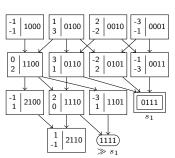




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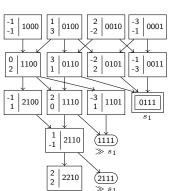




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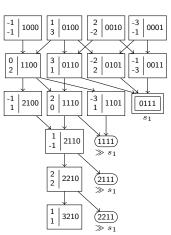




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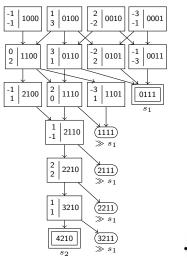




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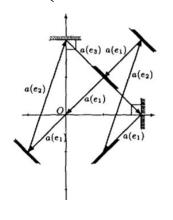
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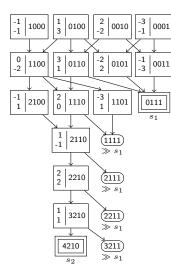






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- Completeness
- Soundness
- ▶ Termination

#### In the theorems:

```
a(x_\downarrow)=0_\downarrow: An n-variate system of homogeneous LDEs. (e_{1\downarrow},\ldots,e_{n\downarrow}): The canonical basis of \mathbb{N}^n. \mathcal{B}(a(x_\downarrow)=0_\downarrow): Basis in the set of nontrivial natural solutions of a(x_\downarrow)=0_\downarrow. \|v_\bot\|: Euclidean norm of v_\bot.
```



#### Theorem (Completeness)

Let  $(e_{1\downarrow},\ldots,e_{n\downarrow}),\emptyset\Longrightarrow^*\emptyset,M$  be the sequence of transformations performed by the Contejean-Devie algorithm for  $a(x_{\downarrow})=0_{\downarrow}$ . Then

$$\mathcal{B}(a(x_{\downarrow}) = 0_{\downarrow}) \subseteq M.$$



#### Theorem (Soundness)

Let  $(e_{1\downarrow},\ldots,e_{n\downarrow}),\emptyset\Longrightarrow^*\emptyset,M$  be the sequence of transformations performed by the Contejean-Devie algorithm for  $a(x_{\downarrow})=0_{\downarrow}$ . Then

$$M \subseteq \mathcal{B}(a(x_{\downarrow}) = 0_{\downarrow}).$$



#### Lemma (Limit Lemma)

Let  $v_{1\downarrow}, v_{2\downarrow}, \ldots$  be an infinite sequence satisfying the Contejean-Devie condition for  $a(x_{\downarrow}) = 0_{\downarrow}$ :

▶  $v_{1\downarrow}$  is a basic vector and for each  $i \geq 1$  there exists  $1 \leq j \leq n$  such that  $a(v_{i\downarrow}) \cdot a(e_{j\downarrow}) < 0$  and  $v_{i+1\downarrow} = v_{i\downarrow} + e_{j\downarrow}$ .

Then

$$\lim_{k \to \infty} \frac{\|a(v_{k\downarrow})\|}{k} = 0$$

#### Theorem (Termination)

Let  $v_{1\downarrow}, v_{2\downarrow}, \ldots$  be an infinite sequence satisfying the conditions of the Limit Lemma. Then there exist  $v_{\downarrow}$  and k such that

- $v_{\downarrow}$  is a solution of  $a(x_{\downarrow}) = 0_{\downarrow}$ , and
- $v_{\downarrow} \ll v_{k\downarrow}$ .





## Non-Homogeneous Case

Non-homogeneous linear Diophantine system with m equations and n variables:

$$\begin{cases} a_{11}x_1 & + \dots + & a_{1n}x_n & = & b_1 \\ \vdots & & \vdots & & \vdots \\ a_{m1}x_1 & + \dots + & a_{mn}x_n & = & b_m \end{cases}$$

- a's and b's are integers.
- ▶ Matrix form:  $a(x_{\downarrow}) = b_{\downarrow}$ .



#### Non-Homogeneous Case. Solving Idea

Turn the system into a homogeneous one, denoted  $S_0$ :

$$\begin{cases}
-b_1x_0 + a_{11}x_1 + \cdots + a_{1n}x_n = 0 \\
\vdots & \vdots & \vdots \\
-b_mx_0 + a_{m1}x_1 + \cdots + a_{mn}x_n = 0
\end{cases}$$

- ▶ Solve  $S_0$  and keep only the solutions with  $x_0 \le 1$ .
- $x_0 = 1$ : a minimal solution for  $a(x_{\downarrow}) = b_{\downarrow}$ .
- $x_0 = 0$ : a minimal solution for  $a(x_{\downarrow}) = 0_{\downarrow}$ .
- ▶ Any solution of the non-homogeneous system  $a(x_{\downarrow}) = b_{\downarrow}$  has the form  $x_{\downarrow} + y_{\downarrow}$  where:
  - $x_{\downarrow}$  is a minimal solution of  $a(x_{\downarrow}) = b_{\downarrow}$ .
  - $y_{\downarrow}$  is a linear combination (with natural coefficients) of minimal solutions of  $a(x_{\downarrow}) = 0_{\downarrow}$ .



