# Logic Programming Unification

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# Unification algorithm: The heart of the computation model of logic programs.



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# **Substitution**

### Definition (Substitution)

A substitution is a finite set of the form

$$\theta = \{v_1 \mapsto t_1, \ldots, v_n \mapsto t_n\}$$

- v<sub>i</sub>'s: distinct variables.
- $t_i$ 's: terms with  $t_i \neq v_i$ .
- Binding:  $v_i \mapsto t_i$ .

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### Substitution Application

### Definition (Substitution application)

Substitution  $\theta = \{v_1 \mapsto t_1, \dots, v_n \mapsto t_n\}$  applied to an expression *E*,

#### Eθ

(the *instance* of *E* wrt  $\theta$ ): Simultaneously replacing each occurrence of  $v_i$  in *E* with  $t_i$ .

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# Substitution Application

#### Example (Application)

$$E = p(x, y, f(a)).$$
  

$$\theta = \{x \mapsto b, y \mapsto x\}.$$
  

$$E\theta = p(b, x, f(a)).$$

Note that x was not replaced second time.

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# Composition

### Definition (Substitution Composition)

Given two substitutions

$$\theta = \{ \mathbf{v}_1 \mapsto \mathbf{t}_1, \dots, \mathbf{v}_n \mapsto \mathbf{t}_n \}$$
  
$$\sigma = \{ \mathbf{u}_1 \mapsto \mathbf{s}_1, \dots, \mathbf{u}_m \mapsto \mathbf{s}_m \},$$

their *composition*  $\theta \sigma$  is obtained from the set

$$\{ \mathbf{V}_1 \mapsto \mathbf{t}_1 \sigma, \dots, \mathbf{V}_n \mapsto \mathbf{t}_n \sigma, \\ \mathbf{U}_1 \mapsto \mathbf{S}_1, \dots, \mathbf{U}_m \mapsto \mathbf{S}_m \}$$

by deleting

• all 
$$u_i \mapsto s_i$$
's with  $u_i \in \{v_1, \ldots, v_n\}$ ,

• all 
$$v_i \mapsto t_i \sigma$$
's with  $v_i = t_i \sigma$ .

# Substitution Composition

### Example (Composition)

$$\theta = \{ \mathbf{x} \mapsto f(\mathbf{y}), \mathbf{y} \mapsto \mathbf{z} \}.$$
  
$$\sigma = \{ \mathbf{x} \mapsto \mathbf{a}, \mathbf{y} \mapsto \mathbf{b}, \mathbf{z} \mapsto \mathbf{y} \}.$$
  
$$\theta \sigma = \{ \mathbf{x} \mapsto f(\mathbf{b}), \mathbf{z} \mapsto \mathbf{y} \}.$$

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# **Empty Substitution**

Empty substitution, denoted  $\varepsilon$ :

- Empty set of bindings.
- $E\varepsilon = E$  for all expressions E.

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### Properties

#### Theorem

 $\begin{aligned} \theta \varepsilon &= \varepsilon \theta = \theta. \\ (\boldsymbol{E} \theta) \sigma &= \boldsymbol{E}(\theta \sigma). \\ (\theta \sigma) \lambda &= \theta(\sigma \lambda). \end{aligned}$ 

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# Example (Properties)

### Example

Given:

$$\begin{aligned} \theta &= \{ \mathbf{x} \mapsto f(\mathbf{y}), \mathbf{y} \mapsto \mathbf{z} \}. \\ \sigma &= \{ \mathbf{x} \mapsto \mathbf{a}, \mathbf{z} \mapsto \mathbf{b} \}. \\ \mathbf{E} &= p(\mathbf{x}, \mathbf{y}, g(\mathbf{z})). \end{aligned}$$

Then

$$\begin{aligned} \theta \sigma &= \{ \mathbf{x} \mapsto f(\mathbf{y}), \mathbf{y} \mapsto \mathbf{b}, \mathbf{z} \mapsto \mathbf{b} \} \\ \mathbf{E} \theta &= p(f(\mathbf{y}), \mathbf{z}, \mathbf{g}(\mathbf{z})) \\ (\mathbf{E} \theta) \sigma &= p(f(\mathbf{y}), \mathbf{b}, \mathbf{g}(\mathbf{b})) \\ \mathbf{E}(\theta \sigma) &= p(f(\mathbf{y}), \mathbf{b}, \mathbf{g}(\mathbf{b})) . \end{aligned}$$

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### **Renaming Substitution**

### Definition (Renaming Substitution)

 $\{x_1 \mapsto y_1, \dots, x_n \mapsto y_n\}$  is a *renaming substitution* iff  $y_i$ 's are distinct variables.

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### Renaming an Expression

#### Definition (Renaming Substitution for an Expression)

Let V be the set of variables of an expression E.

A substitution

$$\theta = \{x_1 \mapsto y_1, \ldots, x_n \mapsto y_n\}$$

is a renaming substitution for E iff

•  $\theta$  is a renaming substitution, and

• 
$$\{x_1,\ldots,x_n\} \subseteq V$$
, and

• 
$$(V \setminus \{x_1, \ldots, x_n\}) \cap \{y_1, \ldots, y_n\} = \emptyset.$$

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### **Definition** (Variant)

Expression *E* and expression *F* are *variants* iff there exist substitutions  $\theta$  and  $\sigma$  such that

• 
$$F\sigma = E$$
.

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### Variants and Renaming

#### Theorem

Expression E and expression F are variants iff there exist renaming substitutions  $\theta$  and  $\sigma$  such that

• 
$$F\sigma = E$$
.

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### Instantiation Quasi-Ordering

### Definition (More General Substitution)

A substitution  $\theta$  is *more general* than a substitution  $\sigma$ , written  $\theta \leq \sigma$ , iff there exists a substitution  $\lambda$  such that

 $\theta \lambda = \sigma.$ 

The relation  $\leq$  on substitutions is called the *instantiation quasi-ordering*.

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# Instantiation Quasi-Ordering

#### Example (More General)

Let  $\theta$  and  $\sigma$  be the substitutions:

$$\theta = \{ \mathbf{x} \mapsto \mathbf{y}, \mathbf{u} \mapsto f(\mathbf{y}, \mathbf{z}) \},\$$
  
$$\sigma = \{ \mathbf{x} \mapsto \mathbf{z}, \mathbf{y} \mapsto \mathbf{z}, \mathbf{u} \mapsto f(\mathbf{z}, \mathbf{z}) \}.$$

Then  $\theta \leq \sigma$  because  $\theta \lambda = \sigma$  where

$$\lambda = \{ \mathbf{y} \mapsto \mathbf{z} \}.$$

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### Unifier

### Definition (Unifier of Expressions)

A substitution  $\theta$  is a *unifier* of expressions *E* and *F* iff

$$E\theta = F\theta.$$

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# Unifier

### Example (Unifier of Expressions)

Let *E* and *F* be two expressions:

$$E = f(x, b, g(z)),$$
  

$$F = f(f(y), y, g(u)).$$

Then  $\theta = \{ x \mapsto f(b), y \mapsto b, z \mapsto u \}$  is a unifier of *E* and *F*:

 $E\theta = f(f(b), b, g(u)),$  $F\theta = f(f(b), b, g(u)).$ 

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# Unifier

### Definition (Unifier of a Set of Expression Pairs)

 $\sigma$  is a unifier of a set of expression pairs

$$\{\langle E_1, F_1 \rangle, \ldots, \langle E_n, F_n \rangle\}$$

iff  $\sigma$  is a unifier of  $E_i$  and  $F_i$  for each  $1 \le i \le n$ , i.e., iff

$$E_1 \sigma = F_1 \sigma,$$
  
...,  
$$E_n \sigma = F_n \sigma$$

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### Most General Unifier

#### Definition (MGU)

A unifier  $\theta$  of *E* and *F* is most general iff  $\theta$  is more general than any other unifier of *E* and *F*.

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### Unifiers and MGU

### Example (Unifiers)

Let *E* and *F* be two expressions:

E = f(x, b, g(z)),F = f(f(y), y, g(u)).

Unifiers of *E* and *F* (infinitely many):

. . .

$$\begin{aligned} \theta_1 &= \{ x \mapsto f(b), y \mapsto b, z \mapsto u \}, \\ \theta_2 &= \{ x \mapsto f(b), y \mapsto b, u \mapsto z \}, \\ \theta_3 &= \{ x \mapsto f(b), y \mapsto b, z \mapsto a, u \mapsto a \}, \\ \theta_4 &= \{ x \mapsto f(b), y \mapsto b, z \mapsto u, w \mapsto d \} \end{aligned}$$

# Unifiers and MGU

#### Example (MGU)

Let *E* and *F* be expressions from the previous example:

$$E = f(x, b, g(z)), \ F = f(f(y), y, g(u)).$$

#### MGU's of E and F:

$$\begin{array}{l} \theta_1 = \{ x \mapsto f(b), y \mapsto b, z \mapsto u \}, \\ \theta_2 = \{ x \mapsto f(b), y \mapsto b, u \mapsto z \}. \end{array}$$

 $\begin{array}{ll} \theta_1 \leq \theta_2 & \quad \theta_2 = \theta_1 \lambda_1 \text{ with } \lambda_1 = \{ u \mapsto z \}. \\ \theta_2 \leq \theta_1 & \quad \theta_1 = \theta_2 \lambda_2 \text{ with } \lambda_2 = \{ z \mapsto u \}. \end{array}$ 

Note:  $\lambda_1$  and  $\lambda_2$  are renaming substitutions.

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# Equivalence of mgu-s

#### Theorem

Most general unifier of two expressions is unique up to variable renaming

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# Unification Algorithm

Rule-based approach.

• General form of rules:

$$\begin{array}{l} \mathsf{P}; \ \sigma \Longrightarrow \mathsf{Q}; \ \theta \ \text{ or } \\ \mathsf{P}; \ \sigma \Longrightarrow \bot. \end{array}$$

- $\perp$  denotes failure.
- $\sigma$  and  $\theta$  are substitutions.
- *P* and *Q* are sets of expression pairs:  $\{\langle E_1, F_1 \rangle, \dots, \langle E_n, F_n \rangle\}.$

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# **Unification Rules**

### Trivial:

$$\{\langle \mathbf{s}, \mathbf{s} \rangle\} \cup \mathbf{P}'; \ \sigma \Longrightarrow \mathbf{P}'; \ \sigma.$$

#### **Decomposition:**

$$\{ \langle f(\mathbf{s}_1, \dots, \mathbf{s}_n), f(t_1, \dots, t_n) \rangle \} \cup P'; \ \sigma \Longrightarrow \\ \{ \langle \mathbf{s}_1, t_1 \rangle, \dots, \langle \mathbf{s}_n, t_n \rangle \} \cup P'; \ \sigma.$$

if  $f(s_1,\ldots,s_n) \neq f(t_1,\ldots,t_n)$ .

### Symbol Clash:

$$\{\langle f(s_1,\ldots,s_n), g(t_1,\ldots,t_m)\rangle\} \cup P'; \sigma \Longrightarrow \bot$$

if  $f \neq g$ .

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# Unification Rules (Contd.)

### **Orient:**

$$\{\langle t, \mathbf{X} \rangle\} \cup \mathbf{P}'; \ \sigma \Longrightarrow \{\langle \mathbf{X}, \mathbf{t} \rangle\} \cup \mathbf{P}'; \ \sigma,$$

if t is not a variable.

### **Occurs Check:**

$$\{\langle \mathbf{X}, \mathbf{t} \rangle\} \cup \mathbf{P}'; \ \sigma \Longrightarrow \bot,$$

if *x* occurs in *t* and  $x \neq t$ .

### Variable Elimination:

$$\{\langle \mathbf{x}, \mathbf{t} \rangle\} \cup \mathbf{P}'; \ \sigma \Longrightarrow \mathbf{P}'\theta; \ \sigma\theta,$$

if *x* does not occur in *t*, and  $\theta = \{x \mapsto t\}$ .

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# Unification Algorithm

In order to unify expressions  $E_1$  and  $E_2$ :

- Create initial system  $\{\langle E_1, E_2 \rangle\}; \varepsilon$ .
- Apply successively unification rules.

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### **Termination**

#### Theorem (Termination)

The unification algorithm terminates either with  $\perp$  or with  $\emptyset$ ;  $\sigma$ .



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### Theorem (Soundness)

If P;  $\varepsilon \Longrightarrow^+ \emptyset$ ;  $\sigma$  then  $\sigma$  is a unifier of P.



### Completeness

#### Theorem (Completeness)

For any unifier  $\theta$  of P the unification algorithm finds a unifier  $\sigma$  of P such that  $\sigma \leq \theta$ .

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### Theorem (Main Theorem)

If two expressions are unifiable then the unification algorithm computes their Mgu.



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### Example (Failure)

Unify p(f(a), g(x)) and p(y, y).

$$\begin{array}{l} \{ \langle p(f(a), g(x)), p(y, y) \rangle \}; \ \varepsilon \Longrightarrow_{\mathsf{Dec}} \\ \{ \langle f(a), y \rangle, \langle g(x), y \rangle \}; \ \varepsilon \Longrightarrow_{\mathsf{Or}} \\ \{ \langle y, f(a) \rangle, \langle g(x), y \rangle \}; \ \varepsilon \Longrightarrow_{\mathsf{VarEl}} \\ \{ \langle g(x), f(a) \rangle \}; \ \{ y \mapsto f(a) \} \Longrightarrow_{\mathsf{SymCl}} \\ \bot \end{array}$$

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# Examples

#### Example (Success)

Unify p(a, x, h(g(z))) and p(z, h(y), h(y)).

$$\begin{split} &\{\langle p(a, x, h(g(z))), p(z, h(y), h(y))\rangle\}; \ \varepsilon \Longrightarrow_{\mathsf{Dec}} \\ &\{\langle a, z\rangle, \langle x, h(y)\rangle, \langle h(g(z)), h(y)\rangle\}; \ \varepsilon \Longrightarrow_{\mathsf{Or}} \\ &\{\langle z, a\rangle, \langle x, h(y)\rangle, \langle h(g(z)), h(y)\rangle\}; \ \varepsilon \Longrightarrow_{\mathsf{VarEl}} \\ &\{\langle x, h(y)\rangle, \langle h(g(a)), h(y)\rangle\}; \ \{z \mapsto a\} \Longrightarrow_{\mathsf{VarEl}} \\ &\{\langle h(g(a)), h(y)\rangle\}; \ \{z \mapsto a, x \mapsto h(y)\} \Longrightarrow_{\mathsf{Or}} \\ &\{\langle g(a), y\rangle\}; \ \{z \mapsto a, x \mapsto h(y)\} \Longrightarrow_{\mathsf{Or}} \\ &\{\langle y, g(a)\rangle\}; \ \{z \mapsto a, x \mapsto h(y)\} \Longrightarrow_{\mathsf{VarEl}} \\ &\emptyset; \ \{z \mapsto a, x \mapsto h(g(a)), y \mapsto g(a)\}. \end{split}$$

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### Example (Failure)

Unify p(x, x) and p(y, f(y)).

$$\begin{array}{l} \{ \langle \boldsymbol{p}(\boldsymbol{x}, \boldsymbol{x}), \boldsymbol{p}(\boldsymbol{y}, \boldsymbol{f}(\boldsymbol{y})) \rangle \}; \ \varepsilon \Longrightarrow_{\mathsf{Dec}} \\ \{ \langle \boldsymbol{x}, \boldsymbol{y} \rangle, \langle \boldsymbol{x}, \boldsymbol{f}(\boldsymbol{y}) \rangle \}; \ \varepsilon \Longrightarrow_{\mathsf{VarEl}} \\ \{ \langle \boldsymbol{y}, \boldsymbol{f}(\boldsymbol{y}) \rangle \}; \ \{ \boldsymbol{x} \mapsto \boldsymbol{y} \} \Longrightarrow_{\mathsf{OccCh}} \\ \bot \end{array}$$

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### Previous Example on PROLOG

### Example (Infinite Terms)

```
?-p(X,X)=p(Y,f(Y)).
```

```
X = f(f(f(f(f(f(f(f(f(...))))))))))
```

```
Y = f(f(f(f(f(f(f(f(f(...))))))))))
```

Yes

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### Occurrence Check

PROLOG unification algorithm skips Occurrence Check.
Reason: Occurrence Check can be expensive.
Justification: Most of the time this rule is not needed.
Drawback: Sometimes might lead to incorrect answers.

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### **Occurrence Check**

### Example

less(X,s(X)).foo:-less(s(Y),Y).

?- foo.

Yes

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