# Temporal Logic Specifications for Parallel Debugging

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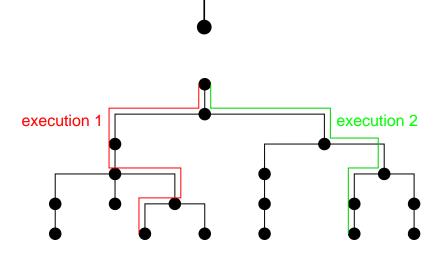
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# Non-Determinism and Parallel Debugging

## **Debugging**

Sequential program:
 one execution per input
 (deterministic execution)

 Parallel program: several executions possible (non-determinism).



Handling non-determinism is a key problem in parallel debugging.

#### Sources of Non-Deterministim

Assume: message passing model with reliable transfer.

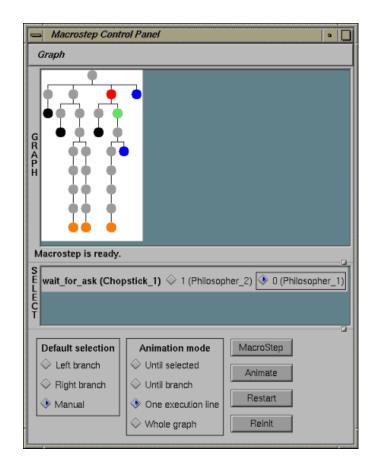
- Non-determinism arise because of
  - alternative receive operations from multiple sources,
  - non-blocking receive operations,
  - effects outside the message passing model.
- MPI Message Passing Interface:
  - MPI\_ANY\_SOURCE: message from any sender accepted.
  - MPI\_IPROBE: non-blocking test for message availability.
  - File communication, multi-threading, etc.

Focus: non-determinism from alternative receive operations.

## P-GRADE Macrostep Debugging

- MTA SZTAKI and SGI
- Controlled selection of alternative inputs
- Manual or automated traversal of state tree

http://www.lpds.sztaki.hu/projects/p-grade



#### Idea

How to further aid debugging of non-deterministic parallel programs?

• Sequential programs: debugging crucially aided by assertions.

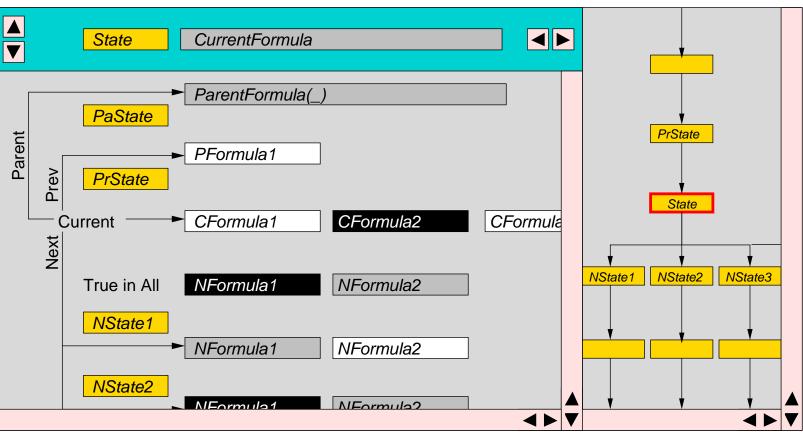
Property that must be true in denoted state.

- Parallel programs: how to employ assertions?
  - State distributed among processes  $\Rightarrow$  need to construct consistent global state.
  - Multiple state sequences possible  $\Rightarrow$  assertion must be designed to hold in every sequence.
  - Useful properties involve multiple states  $\Rightarrow$  assertion must talk about whole state sequence.

Let assertions be generated from formal program specifications.

#### **Macrostep Specification Checking**

# Formula View State Tree View



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# **Temporal Logic Specifications**

#### **Example: Mutual Exclusion**

```
P_0:
      c := -1; w := \langle \rangle
      loop
         (s_0, m_0) := receive()
         if m_0 = "enter" then
a:
            if c_0 = -1
               then c_0 := s_0; send(s_0, \text{``okay''})
b:
               else w_0 := w_0 \|\langle s_0 \rangle
            end
         else if m = \text{"exit"} then
            c_0 := -1
            if w_0 \neq \langle \rangle then
               c_0 := \text{head}(w_0); \ w_0 := \text{tail}(w_0)
              send(c_0, "okay")
c:
            end
         end
      end
```

```
\begin{aligned} \mathbf{P_{i,i>0}} \colon & & \mathbf{loop} \\ p \colon & & \mathbf{send}(0, \text{ "enter"}) \\ q \colon & & m_i := \mathbf{receive}(0) \\ r \colon & & \underline{\textit{critical region}} \\ & & \mathbf{send}(0, \text{"exit"}) \\ & & \mathbf{end} \end{aligned}
```

## **Crucial Properties**

#### Mutual exclusion:

Always, if client i is in the critical region, then client  $j \neq i$  is not in the critical region.  $\forall i \in 1 \dots n : \Box[\operatorname{at_r}(i) \Rightarrow (\forall j \in 1 \dots n : j \neq i \Rightarrow \neg \operatorname{at_r}(j))]$ 

#### • Progress:

Always, if client i requests access to the critical region, it eventually enters the region.  $\forall i \in 1 \dots n : \Box[\operatorname{at}_{\mathbf{q}}(i) \Rightarrow \Diamond \operatorname{at}_{\mathbf{r}}(i)]$ 

Specification of system functionality from clients' point of view.

## **More Properties**

• No request is lost:

Always, if the client is to send a request, the server eventually receives it:

$$\forall i \in 1..n : \Box[\operatorname{at}_{p}(i) \Rightarrow \Diamond(\operatorname{at}_{a}(i) \land s_{0} = i \land m_{0} = \text{"enter"})]$$

• No request is forgotten:

Always, if server i does not immediately answer the request, it will later answer it:

$$\Box[\operatorname{at_b}(0) \Rightarrow \operatorname{let} i = s_0 \text{ in } \Diamond(\operatorname{at_c}(0) \land c_0 = i)]$$

• No request is added:

Always, if the server grants access to client i, it has previously received a request from i:

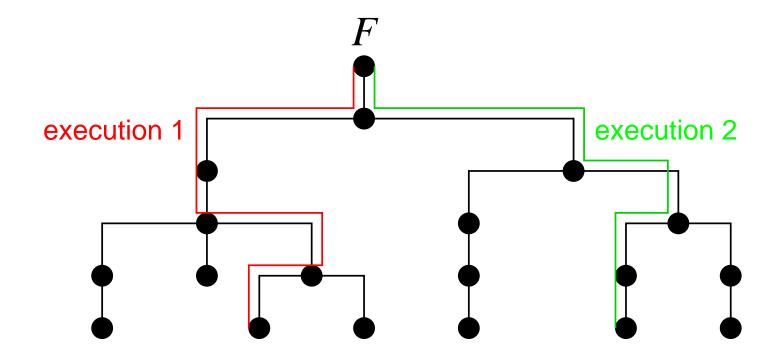
$$\square[\operatorname{at}_{c}(0) \Rightarrow \operatorname{let} i = c_0 \text{ in } \diamondsuit(\operatorname{at}_{a}(0) \land s_0 = i)]$$

Detailed description of system functionality possible.

#### **Temporal Logic Formulas**

- Atomic formulas  $p_n(t_0, \ldots, t_{n-1})$ 
  - Mathematical variables x
  - Program variables  $v_i$
  - Program counters  $at_c(i)$
  - Message buffers  $msgbuf_i$
- Connectives  $\land, \lor, \neg, \Rightarrow, \Leftrightarrow$
- Quantifiers  $\forall x \in D$ ,  $\exists x \in D$ , let x = T
- Temporal operators
  - Always  $\square$
  - Eventually  $\diamondsuit$
  - Leads to  $\rightsquigarrow$
  - Past variants: □ ♦ →

#### **Temporal Logic Specifications**



A temporal logic formula F can express a property about all possible executions of a (non-deterministic, parallel) program.

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# **Specification Calculus**

## **Specification Calculus**

1. Semantics of temporal logic formulas.

Semantics in terms of state sequences.

2. Translation to guarded temporal formulas.

Only knowledge about previous state, current state, next state required.

3. Tree semantics of temporal formulas.

Semantics in terms of state trees.

4. Partial tree semantics of temporal formulas.

Next state may be unknown.

5. Extraction of (previous/current/next)-state formulas.

#### **Temporal Logic Semantics**

Validity of temporal logic formulas:

A temporal formula F is true for a program with initial states  $is \subseteq State$  and next state relation  $ns \subseteq State \times State$ , if it is true for every state sequence induced by is and ns:

```
S(is, ns) := \{s : \mathbb{N} \to \text{State} : s_0 \in is \land \forall i \in \mathbb{N} : (s_i, s_{i+1}) \in ns \}
\cup \{s : \mathbb{N}_n \to \text{State} : s_0 \in is \land \forall i \in \mathbb{N}_{n-1} : (s_i, s_{i+1}) \in ns \land \neg \exists x : (s_{n-1}, x) \in ns \}
\mathbf{T}[[F]]is \ ns : \Leftrightarrow \forall s \in S(is, ns) : \mathbf{T}[[F]]s \ 0
```

Validity of a formula in a non-empty state sequence s:

```
\mathbf{T}[[p_n(t_0,\ldots,t_{n-1})]]s\ i = [[p_n]]([[t_0]]s_i,\ldots,[[t_{n-1}]]s_i)
...
\mathbf{T}[[\Box F]]s\ i \Leftrightarrow \text{true iff } \mathbf{T}[[F]]s\ j = \text{true for all } j \text{ with } i \leq j < |s|
\mathbf{T}[[\diamondsuit F]]s\ i \Leftrightarrow \text{true iff } \mathbf{T}[[F]]s\ j = \text{true for some } j \text{ with } i \leq j < |s|
\mathbf{T}[[\Box F]]s\ i \Leftrightarrow \text{true iff } \mathbf{T}[[F]]s\ j = \text{true for all } j \text{ with } 0 \leq j \leq i
```

#### **Guarded Temporal Formulas**

Guard temporal operators by ○ resp. ⊖ ("next/previous time")

 $\mathbf{G}[[\Box F]] = \mathbf{G}[[F]] \land \circ_{\mathrm{true}} \Box F \quad \text{``always''} \quad \text{becomes ``now and next time always''} \\ \mathbf{G}[[\diamondsuit F]] = \mathbf{G}[[F]] \lor \circ_{\mathrm{false}} \Box F \quad \text{``eventually''} \quad \text{becomes ``now or next time event.''} \\ \mathbf{G}[[\Box F]] = \mathbf{G}[[F]] \land \circ_{\mathrm{true}} \Box F \quad \text{``once''} \quad \text{becomes ``now or previous time once''}$ 

. . .

Translation preserves semantics

$$\mathbf{T}[[F]]s \ i \Leftrightarrow \mathbf{T}(\mathbf{G}[[F]])s \ i$$

$$\mathbf{T}[[\circ_v F]]s \ i \Leftrightarrow \text{if} \ i+1=|s| \text{ then } v \text{ else } \mathbf{T}[[F]]s \ (i+1)$$

$$\mathbf{T}[[\circ_v F]]s \ i \Leftrightarrow \text{if} \ i=0 \text{ then } v \text{ else } \mathbf{T}[[F]]s \ (i-1)$$

Only need current state, next state, and previous state.

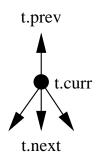
#### **Tree Semantics**



$$T(is, ns) := \{T(\top, i, ns) : i \in is\}$$

$$T(p, i, ns) = t \Leftrightarrow t_{\text{prev}} = p \land t_{\text{curr}} = i$$

$$\land t_{\text{next}} = \text{if } \exists x : (i, x) \in ns \text{ then } \{T(i, x, ns) : (i, x) \in ns\} \text{ else } \{\top\}$$



Semantics of guarded temporal formulas based on trees

```
\mathbf{T}[[p_n(t_0,\ldots,t_{n-1})]]t = [[p_n]]([[t_0]]t_{\mathrm{curr}},\ldots,[[t_{n-1}]]t_{\mathrm{curr}})
...
\mathbf{T}[[\circ_v F]]t \Leftrightarrow \text{ true iff } \mathbf{T}(\mathbf{G}[[F]])x \Leftrightarrow \text{ true for every } x \in t_{\mathrm{next}}
\mathbf{T}[[\circ_v F]]t \Leftrightarrow \text{ true iff } \mathbf{T}(\mathbf{G}[[F]])x \Leftrightarrow \text{ true where } x = t_{\mathrm{prev}}
\mathbf{T}[[\circ_v F]] \top \Leftrightarrow v
\mathbf{T}[[\circ_v F]] \top \Leftrightarrow v
```

## Translate sets of state sequences to (sets of) state trees.

#### **Semantic Relationship**

Validity of formulas over state trees:

$$\mathbf{T}[[GF]]T \Leftrightarrow \text{true iff } \mathbf{T}[[GF]]t \Leftrightarrow \text{true for every } t \in T$$

Relationship to original semantics preserved

$$T[[F]]is \ ns \Leftrightarrow T(G[[F]])F(is, ns)$$

May operate on state trees instead of sequences.

#### **Partial Tree Semantics**

• Replace 2-valued logic in T by 3-valued logic ( $\bot = unknown$ ):

$$\neg_3 \bot = \bot, T \land_3 \bot = \bot, F \land_3 \bot = F, T \lor_3 \bot = T, F \lor_3 \bot = \bot$$

ullet Assume that only part of tree is known ( $\bot =$ unknown subtree).

Tree s is a subtree of t if it equals t except for some  $\bot$  subtrees:

$$s \sqsubseteq t :\Leftrightarrow s = \bot \lor (s_{\text{curr}} = t_{\text{curr}} \land \exists f : s_{\text{next}} \xrightarrow{\text{bij.}} t_{\text{next}} : \forall x \in s_{\text{next}} : x \sqsubseteq f(x))$$

Partial Tree Semantics

$$\mathbf{T}_3[[F]]\perp :\Leftrightarrow \bot$$

Compatibility and monotonicity:

```
t does not contain \perp \Rightarrow \mathbf{T}_3[[F]]t = \mathbf{T}_2[[F]]t
s \sqsubseteq t \Rightarrow \mathbf{T}_3[[F]]s \sqsubseteq \mathbf{T}_3[[F]]t
```

#### **Extraction of State Formulas**

•  $\mathbf{T}(\mathbf{G}[[\Box(p_n(\ldots) \land q_m(\ldots))]])t$ :  $\mathbf{T}(\mathbf{G}[[\Box(p_n(\ldots) \land q_m(\ldots))]])t \Leftrightarrow \text{true}$ iff  $\mathbf{T}(\mathbf{G}[[p_n(\ldots) \land q_m(\ldots)]]) \land \circ \Box(p_n(\ldots) \land q_m(\ldots)))t \Leftrightarrow \text{true}$ iff  $\mathbf{T}(\mathbf{G}[[p_n(\ldots) \land q_m(\ldots)]])t \Leftrightarrow \text{true}$  and  $\mathbf{T}[[\circ \Box(p_n(\ldots) \land q_m(\ldots))]]t \Leftrightarrow \text{true}$ iff  $\mathbf{T}[[p_n(\ldots) \land q_m(\ldots)]]t \Leftrightarrow \text{true}$  and  $\mathbf{T}[[\Box(p_n(\ldots) \land q_m(\ldots))]]x \Leftrightarrow \text{true}$  for  $x \in t_{\text{next}}$ 

#### Extracted Formulas:

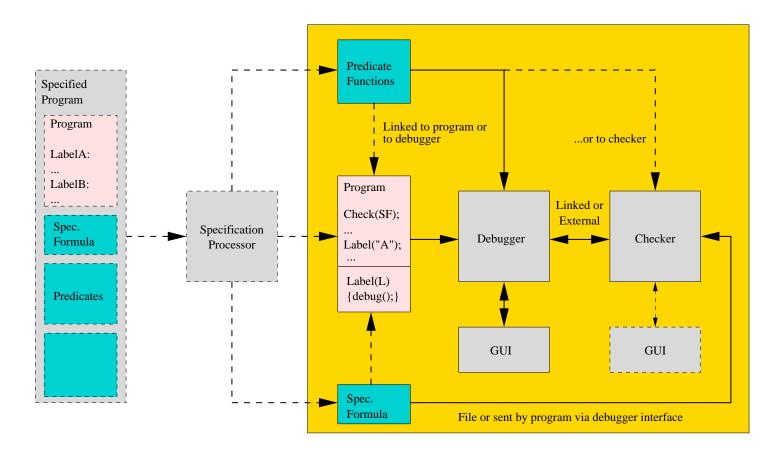
```
Previous state: none (zero or more formulas) 
Current state: p_n(\ldots), q_m(\ldots) (one ore more atomic formulas) 
Next state: \Box(p_n(\ldots) \land q_m(\ldots)) (zero or more formulas)
```

Checking formula yields formulas for previous, current, next state.

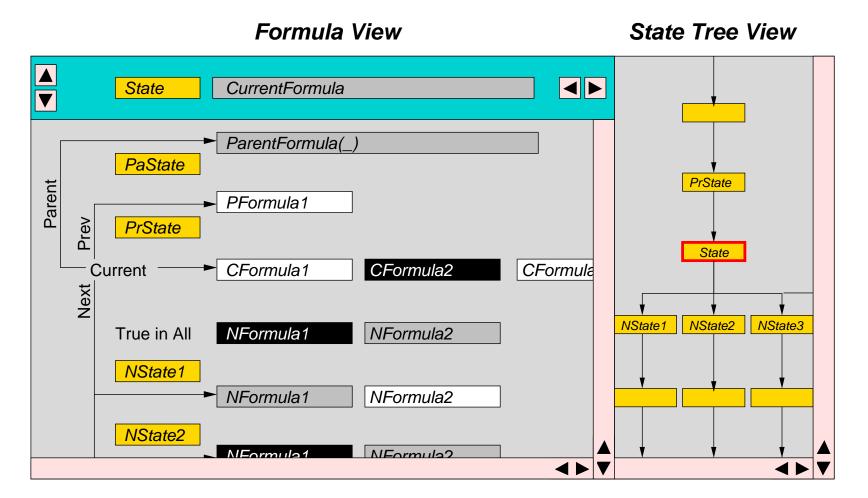
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# **System Architecture and Interfaces**

# **System Architecture**



#### **User Interface**



## Program/Debugger Interface

- Label set by program:
  - label(name);
  - Denotes checking state (in addition to states of receive operations?)
- Functionality of atomic predicate functions:
  - procNumber()
  - getVar(name, procid) (scope?)
  - atLabel(name, procid)
  - msgNumber(procid), msgSender(procid, i), msgContent(procid)
- Possibly: assert (temporal) formula in current state.
  - tassert(formula)
  - current state becomes root of tree for checking the formula.
  - formula as string (or possibly as object) forwarded to checker.

## Debugger/Checker Interface

- General questions:
  - Is checker external program or linked to debugger?
  - If external, own graphical user interface?
- Debugger functionality (used by checker):
  - type State = void\*
    pointer that represents program state in debugger
  - eval(State state, String f, int x0, ...) determine value of named atomic formula in denoted state with given values for the mathematical variables free in the formula.
- Checker functionality (used by debugger):
  - Determine validity of specification with partial state tree.
  - Notify debugger when truth of formula in state has changed (from unknown to true/false).

## **Checker Functionality**

```
interface Node
 // register callback function for value change notification
 static void setNodeFormulaNotify(void (*f)(NodeFormula))
 // register formula to be checked with current node as root
 void setFormula(String f)
 static Node topNode() // constructors
 Node addChild(State state)
 void noMoreChildren()
 State getState() // selectors
 NodeFormula[] getNodeFormulas()
```

## **Checker Functionality**

## **Checker Functionality**

```
interface NodeFormulaP
  int getNumber()
                                    // number of next states
 NodeFormula getNodeFormula(int i) // formula for next state i
 boolean allTrue()
                                    // formula in all states true?
 boolean someFalse()
                                    // formula in some state false?
interface Bool3
 boolean isTrue();
 boolean isFalse();
 boolean isUnknown();
}
```